

Supersymmetric configurations and solutions

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The symmetry of configurations or solutions has to be addressed in the framework of a given theory and its symmetry group.

Any given configuration of a theory breaks ("spontaneously") most of the symmetries of the theory and "preserves" (or leaves unbroken) some subgroup. If the configuration is a solution and is used as a background (or vacuum state) on which the perturbations evolve, these are described by theories whose symmetries are those left unbroken by the background solution. This is the basis of the Higgs mechanism and of the "spontaneous compactification" mechanism invoked in Kaluza-Klein supergravity/superstring theories.

The main difference between these two mechanisms is the absence or presence of gravity. In absence of gravity (i.e. in the fixed Minkowski background of Special Relativistic QFTs) there is a common energy scale for all the vacuum states and the vacuum selection mechanism is the minimization of energy. In presence of gravity only the energy of solutions with common asymptotics that allow for a well-defined notion of energy can be compared. Actually, the asymptotics are associated to a common vacuum solution and, solutions with the same asymptotics can be understood as perturbations over the common vacuum. Thus the relative energies of different vacua cannot be compared and there is no clear vacuum selection mechanism.

This is the root of the "landscape problem" of superstring theory

and, from the previous discussion, it follows that it is a problem of all theories of gravity.

Although there is no vacuum selection mechanism, there is, however, a criterion to distinguish vacua from other solutions: the amount of unbroken symmetry of the solution: vacua have a high degree of symmetry and are, typically (products of) homogeneous spaces with no distinguished points while the solutions that represent excitations over that vacuum have globally less symmetry although it can be recovered asymptotically or in other limits.

Solutions that preserve many symmetries are also relevant for other reasons (they can be used to describe idealized situations with great success (Schwarzschild, Kerr...)) and, moreover, they are simpler to find. This makes them very interesting objects of study.

In the context of theories which are invariant under (local or global) supersymmetry transformations we can consider solutions that preserve some of them. They are called supersymmetric solutions (or configurations, if we do not impose the e.o.m.) or BPS solutions because, often, they satisfy 1st-order differential equations similar to the Bogomol'nyi equations satisfied by the 't Hooft-Polyakov monopole in the Bogomol'nyi-Prasad-Sommerfield (BPS) limit.

The subject of these lectures is the construction and study of the supersymmetric solutions of a particularly interesting class of theories which are invariant under local supersymmetry transformations: $\mathcal{N}=1, 2=5$ supergravities. Before studying the solutions (and how they are found) we need to understand well the theories and, more generally, what are the main features of supersymmetric solutions.

Killing spinor equations

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Field theories invariant under linear supersymmetry transformations must have bosonic ϕ^B and fermionic ϕ^F fields (commuting and anti-commuting). They are, respectively, tensor and spinor (or tensor-spinor) fields and their quantum excitations are particle states of integer or half-integer spin.

The infinitesimal parameters of the supersymmetry transformations are spinors ϵ . If they are only allowed to be constants or constant times fixed functions, the supersymmetry is said to be global. When they can be arbitrary spacetime functions, the supersymmetry is local.

Local linear supersymmetry always implies invariance under g.c.t.s and the presence of a dynamical metric: gravity \Rightarrow supergravity

One of the reasons for this is that supersymmetry transformations alone do not form a closed algebraic structure (group) but close on standard bosonic spacetime symmetry transformations. Supersymmetry is a spacetime symmetry and not just an internal symmetry. Global supersymmetry is the Special Relativity of superspace (an extension of Minkowski spacetime with odd coordinates). Local supersymmetry is the General Relativity of curved superspace. Finding supersymmetry would be much more than finding another internal symmetry because, gravity couples to everything and everything exists in spacetime.

Generically, infinitesimal susy transf. have the form

$$\begin{cases} \delta_\epsilon \phi^B = \epsilon \phi^F (\times \phi^B); \\ \delta_\epsilon \phi^F = \partial \epsilon + (\phi^B + \phi^F \phi^F) \epsilon; \end{cases} \quad \partial \epsilon = 0 \text{ in the global case}$$

A configuration ϕ would be supersymmetric if, for some ϵ (Killing spinor)

$$\begin{cases} \delta_\epsilon \phi^F = 0; \\ \delta_\epsilon \phi^B = 0; \end{cases}$$

Classically only purely bosonic configurations are considered $\phi^F = 0$

The condition reduces then to $\boxed{\delta_\varepsilon \phi^\dagger = \mathcal{D}\varepsilon + \rho^\mu \varepsilon = 0}$
Killing spinor equations (KSE)

ε : Killing spinor of the field configuration ϕ^b , $\phi^\dagger = 0$.

The KSE that contains the derivative of ε can be written in the form $\mathcal{D}\varepsilon = 0$ where \mathcal{D} is a linear differential operator called supercovariant derivative. It is covariant w.r.t. all the transformations acting on ε because the spinor on the l.h.s. $\delta_\varepsilon \phi^\dagger$ must transform in the same way. Thus, it is, at least Lorentz-covariant (contains the spin connection ω_μ^{ab}) but can contain additional connections: gauge, if the spinors are charged ("gauged supergravities") and the pullbacks of the connections of the scalar manifolds (if any), related to R-symmetry.

The Killing spinors span a finite-dimensional vector space of unbroken supersymmetries. Maximally supersymmetric if the dimension is that of the spinor. ($\frac{1}{2}$ BPS, $\frac{1}{4}$ BPS ...) These are the candidates to vacua of the supergravity theory.

Superalgebras of symmetry

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The Killing operators of a bosonic field configuration see the odd generators of the super(Lie) group of symmetry of the configuration (the theory is invariant under the infinite-dimensional supergroup of general superparametrizations.) How can we find it?

- i) Find all the Killing operators K_I^α $\xrightarrow{\text{associate.}}$ Q_I odd
- ii) Find all the Killing vectors k_A^μ $\xrightarrow{\hspace{2cm}}$ T_A even
- iii) Find all the Killing gauge parameters α_M $\xrightarrow{\hspace{2cm}}$ B_M even
(intend to leave ϕ^i invariant)

We want to find the structure constants of the (anti-) commutators of all the generators.

The k_A form a closed Lie algebra by themselves

$$[k_A, k_B] = -f_{AB}^C k_C \Rightarrow [P_A, P_B] = f_{AB}^C P_C;$$

$$\mathcal{L}_{k_A} k_B \Rightarrow [B_M, B_N] = -f_{MN}^P B_P;$$

$$[B_M, P_A] = -f_{MA}^N B_N ?$$

From $\mathcal{L}_{k_A} B_M = -f_{MA}^N B_N$; $(T_A)^N_M$ a rep. of the isometry algebra on the B^i

The difficult part is to compute

$$\{Q_I, Q_J\} = f_{IJ}^A P_A + f_{IJ}^M B_M;$$

$$[Q_I, P_A] = f_{IA}^J Q_J;$$

$$[Q_I, B_M] = f_{IM}^J Q_J;$$

we can interpret them as the action of the bosonic generators on the fermionic ones.

Easy: the spinors of the theory (in particular the susy t. parameters) have well-defined transformation rules under internal symmetries.

More difficult: the standard Lie derivative is not compatible with ("covariant under") Lorentz (spin) or internal transformations. \rightarrow Kosman Lie derivative

Koerner defined a generalisation of the Lie derivative for spinors.
A generalisation for any object transforming in the linear representation ρ of the Lorentz group is, for any vector V^μ

$$\begin{aligned} \mathbb{L}_V T &\equiv \underbrace{V^\mu \nabla_\mu T}_{\text{Fermi (off-shell + Lorentz) covariant derivative}} + \underbrace{\frac{1}{2} \nabla_{[a} V_{b]} \rho_{\rho}(\text{Mob}) T}_{\text{compensating Lorentz transformation}} \\ &= \underbrace{V^\mu \partial_\mu T}_{\mathbb{L}_V T} - \frac{1}{4} \left(V^\mu \omega_{\mu}^{ab} - 2 \nabla_{[a} V^{b]} \right) \rho_{\rho}(\text{Mob}) T \end{aligned}$$

$$\mathbb{L}_V T_{\rho_1 \dots \rho_n}^{v_1 \dots v_m} = \mathbb{L}_V T_{\rho_1 \dots \rho_n}^{v_1 \dots v_m} - \frac{1}{4} \left(\dots \right) \rho_{\rho}(\text{Mob}) T_{\rho_1 \dots \rho_n}^{v_1 \dots v_m}$$

The desired properties only hold when V^μ is a KV or CKV

- 1) Leibnitz rule
- 2) $[\mathbb{L}_{k_1}, \mathbb{L}_{k_2}] = \mathbb{L}_{[k_1, k_2]} T$ } Lie bracket
- 3) Linearity in V } Lie algebra structure

Further

$$4) \mathbb{L}_k \delta^a = 0$$

5) Preserves the Clifford action of vectors V^μ on spinors ψ $V \cdot \psi =$

$$V \cdot \psi = V^\mu \gamma_\mu \psi = V^\mu e^a{}_\mu \gamma_a \psi = V^a \gamma_a \psi = \not{V} \psi$$

$$[\mathbb{L}_k, \not{V}] \psi = [k, V] \cdot \psi$$

$$6) \text{ (Only for KV) } [\mathbb{L}_k, \nabla_V] T = \nabla_{[k, V]} T$$

7) If we include additional connections $[\mathbb{L}_k, \not{Q}_V] \epsilon = \not{\partial}_{[k, V]} \epsilon$

\Rightarrow It follows that it transforms KS into KS.

$$\Rightarrow -\mathbb{L}_{k_A} \epsilon_I = \int_{A I}^J \epsilon_J \quad \rightarrow \quad [Q_I, P_A] = \int_{A I}^J Q_J;$$

Finally $\bar{\epsilon}_I^\alpha \rightarrow \bar{\epsilon}_\alpha$ (conjugation (Dirac, Majorana))

$$\bar{\epsilon}_I^\alpha \epsilon_J^\beta = C_{IJ} \delta_\alpha^\beta + C_{IJ}^a \gamma_a^\beta{}_\alpha + \frac{1}{2} C_{IJ}^{ab} \gamma_{ab}^\beta{}_\alpha + \dots$$

Which terms do actually occur on the r.h.s. depends on the dimension etc. However, we always have $C_{IJ}^a \neq 0$ and, furthermore

$$C_{IJ}^a = f_{IJ}^A R_A^a$$

$$\bar{\epsilon}^\alpha \epsilon \equiv \bar{\epsilon}_I^\alpha \gamma^{\alpha\beta} \epsilon_J^\beta \sim f_{IJ}^A R_A^a$$

The rest of the terms correspond to parameters of gauge transformations of the fields of the theory $\delta A_\mu = \partial_\mu \varphi^{(0)}$, $\delta B_{\mu\nu} = 2 \partial_{[\mu} \varphi_{\nu]}^{(1)}$ etc

$$\Rightarrow \int d^4x B_M$$

The tensor bilinears that one constructs from the KSs contain a great deal of information about the bosonic fields of the configuration through their spectrum and internal symmetries.

Demanding unbroken supersymmetry is much more restrictive than demanding some spacetime symmetry.

On the other hand, the bilinears contain the same information as the spinors with respect to the bosonic fields.

Killing spinor identities

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These identities show how powerful the requirement of unbroken supersymmetry is compared with standard symmetry.

Consider a theory with linearly realized local supersymmetry. The action S is invariant under $\delta_\epsilon \phi^b, \delta_\epsilon \phi^f$:

$$\delta_\epsilon S = 0 = \int \left\{ \frac{\delta S}{\delta \phi^b} \delta_\epsilon \phi^b + \frac{\delta S}{\delta \phi^f} \delta_\epsilon \phi^f \right\} \quad (\text{up to t.d.})$$

Let us take the functional derivative of this identity w.r.t. the fermionic fields:

$$\begin{aligned} 0 &= \frac{\delta}{\delta \phi^{f^1}} \left\{ \frac{\delta S}{\delta \phi^b} \delta_\epsilon \phi^b + \frac{\delta S}{\delta \phi^{f^2}} \delta_\epsilon \phi^{f^2} \right\} = \\ &= \frac{\delta^2 S}{\delta \phi^{f^1} \delta \phi^b} \delta_\epsilon \phi^b + \frac{\delta S}{\delta \phi^b} \frac{\delta}{\delta \phi^{f^1}} (\delta_\epsilon \phi^b) + \\ &+ \frac{\delta^2 S}{\delta \phi^{f^1} \delta \phi^{f^2}} \delta_\epsilon \phi^{f^2} + \frac{\delta S}{\delta \phi^{f^2}} \frac{\delta}{\delta \phi^{f^1}} (\delta_\epsilon \phi^{f^2}) = 0 \end{aligned}$$

Now we set to zero all the fermionic fields $\phi^f = 0 \Rightarrow \begin{cases} \delta_\epsilon \phi^b = 0 \\ \frac{\delta S}{\delta \phi^{f^2}} = 0 \end{cases}$

$$\left(\frac{\delta S}{\delta \phi^b} \frac{\delta}{\delta \phi^{f^1}} (\delta_\epsilon \phi^b) + \frac{\delta^2 S}{\delta \phi^{f^1} \delta \phi^{f^2}} \delta_\epsilon \phi^{f^2} \right) \Big|_{\phi^f = 0} = 0$$

Then, require the field configurations to be supersymmetric $\delta_\epsilon \phi^f = 0$

$$\boxed{\left. \frac{\delta S}{\delta \phi^b} \Big|_{\phi^f = 0} \frac{\delta}{\delta \phi^{f^1}} (\delta_\epsilon \phi^b) \Big|_{\phi^f = 0} = 0 \right.}_{\text{Killing}} \quad \text{KSI's}$$

\Rightarrow Certain combinations of the equations of motion of the bosonic fields are automatically satisfied.

If one looks for supersymmetric solutions among the supersymmetric configurations only a few independent e.o.m.'s to be imposed.

Other general properties of susy solutions

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- BHs : - vanishing temperature \Rightarrow extremal \Rightarrow usually one can have many in static equilibrium.
- interpolating between maximally supersymmetric solutions
 - \rightarrow asymptotically (Drinkowski, AdS)
 - \rightarrow at the event horizon ($AdS_2 \times S^3$ or similar)

\Downarrow
Supersymmetric near-horizon geometries can be determined more easily! They can be very interesting in $d > 4$!

- Strings, branes : generalisation of the above features + possible interactions.

- Stationary gravitational waves (Hfr waves)

- Gödel-like spacetimes (\Rightarrow supersymmetry does not exclude CTCs)

N=1, d=5 Supergravities

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Supersymmetric theories are labeled by the number N of uncounted supersymmetry parameters, the dimension of the spacetime d and the matter content and gauged symmetries.

$N=1$ means there is only one parameter: a spinor. The smallest spinor representation in $d=5$ $(1,4)$ has 8 real independent parameters but we cannot construct a Lorentz-invariant theory if we use less than 8 imposing constraints on the spinor. Sometimes people refer to these theories as theories with "8 supercharges" and also as $N=2, d=5$ theories because 8 independent spinor components correspond to 2 minimal spinors in $d=4$ (Weyl & Majorana).

Why $N=1$? The more (super) symmetry, the more constrained theories are: $N=4$ is unique, but there are many models of $N=1, d=5$ supergravity with interesting properties (related to $N=2, d=4$ models also very interesting because they are the simplest that admit supersymmetric BHs).

Why $d=5$? Most of what we find in the $N=2, d=4$ models can be uplifted to $N=1, d=5$. But $d=5$ is a far richer arena because in $d=5$ BH uniqueness theorems and the theorems on the topology of BH event horizons are violated (with no need of cosmological constant).

Thus, we find black rings, black strings...

Moreover, in $d=5$ we find AdS_3 factors in near-horizon geometries which are related to 2-d CFTs.

Spinors, gamma matrices and identities

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The structure of a supersymmetric theory is dictated by the properties of its spinors and γ matrices (Clifford algebra)

In $d=5$ there are no \mathbb{Z}_2 or Majorana spinors. The minimal spinor ψ^i is a Dirac 4-component complex spinor. However, there is another way of looking at it: as a symplectic-Majorana spinor ψ^i , $i=1,2$. As we are going to see, only by recasting Dirac spinors in this way we can make manifest an underlying symmetry of the theory called R-symmetry and which in this case corresponds to the global $SU(2) \sim Sp(1)$ group acting on the fundamental representation over the spinor indices $i=1,2$.

R-symmetry is the group of outer automorphisms of the $N=1, d=5$ supersymmetry algebra and we expect all $N=1, d=5$ theories to be invariant under them (but do not associate that superalgebra to the SUGRA as you do not associate the Poincaré algebra to GR).

To define symplectic-Majorana spinors, we first review the γ -matrices

$$\{\gamma^a, \gamma^b\} = +2\eta^{ab} \quad ; \quad (\eta^{ab}) = \text{diag}(+ - - - -) \quad 4 \times 4 (\gamma^a)^T_{\beta}$$

There is no Majorana (purely real or imaginary) representation. We can take $\gamma^0 - \gamma^3$ imaginary (same as in $d=4$) and $\gamma^4 \equiv \gamma_0 \gamma_1 \gamma_2 \gamma_3 \in \mathbb{R}$

$$\rightarrow \gamma^0 \gamma^1 \gamma^2 \gamma^3 \gamma^4 = +1$$

Dirac conjugation matrix D

$$D_{\pm}^{-1} \gamma^a D_{\pm} = \pm \gamma^a$$

$$\Gamma_5(M_{ab}) \sim \gamma_{ab}$$

$$D^{-1} \Gamma_5(M_{ab})^T D = -\Gamma_5(M_{ab})$$

$$\psi^{\alpha} \rightarrow \Psi_{\alpha} = (\psi^{\beta})^* D_{\beta\alpha}$$

(Ψ_{α} transforms covariantly if ψ^{α} transforms contravariantly)

Charge conjugation matrix C

$$C_{\pm}^{-1} \gamma^a C_{\pm} = \pm \gamma^a$$

$$C^{-1} \Gamma_5(M_{ab})^T C = -\Gamma_5(M_{ab})$$

$$\psi^c_{\alpha} = \psi^{\beta} C_{\beta\alpha}$$

(ψ^c_{α} covariant)

Majorana condition $\bar{\psi} = \psi_c \Rightarrow$ (Majorana spinor (1/2 indep. comp.))

In $d=5$ $D_{(+)} = i\gamma^0$; $C_{(+)} = i\gamma^0\gamma^4$ and the Majorana condition reads

$$\psi^+ D = \psi^T C; \quad (\psi^{*T} i\gamma^0 = \psi^T i\gamma^0\gamma^4) - i\gamma^0; \quad \psi^{*T} = -\psi^T \gamma^4;$$

$$\psi^* = -\gamma^4 T \psi$$

$$\gamma^4 \text{ real, unitary and } (\gamma^4)^2 = -1; \quad \gamma^4 T = \gamma^4 T = -\gamma^4 \quad \left. \begin{array}{l} \text{mit } (\gamma^4)^2 = -1 \\ \text{and } \rightarrow \gamma^4 T \end{array} \right\} \boxed{\psi^* = \gamma^4 \psi}$$

This condition is not consistent: $(\psi^* = \gamma^4 \psi)^* \Rightarrow \psi = \gamma^4 \psi^* \Rightarrow \psi^* = -\gamma^4 \psi$

The only possibility is to take a pair of spinors ψ^i $i=1,2$ (or several pairs)

and suppose
$$\boxed{\psi^{*i} = \Omega_{ij} \gamma^4 \psi^j \quad \oplus \quad \Omega_{ij} \Omega_{jk} = -\delta_{ik}}$$

Symplectic-Majorana condition $\boxed{\bar{\psi}^i = \Omega_{ij} \psi^j_c} = \psi_c^i$

There is a natural action of $USp(N)$ on (pairs of) symplectic-Majorana spinors that preserves their nature (the above condition):

$$\psi'^i = \Lambda^i_j \psi^j; \quad \bar{\psi}'^i = (\Lambda^i_j)^* \bar{\psi}^j;$$

$$(\Lambda^{*-1})^m_i \left[(\Lambda^i_j)^* \bar{\psi}^j = \Omega_{ik} \Lambda^k_l \psi^l_c \right] \quad \bar{\psi}^m = (\Lambda^{*-1})^m_i \Omega_{ik} \Lambda^k_l \psi^l_c$$

$$(\Lambda^{*-1}) \Omega \Lambda = \Omega; \quad \text{Solved by } \Lambda^+ = \Lambda^{-1} \in U(N) \quad \Omega \text{ real} \\ \Lambda^T \Omega \Lambda = \Omega \in Sp(N)$$

The structures that occur in the supergravity theory are related to the possible spinor bilineals one can construct with just N pairs of $S=1$ spinors $\bar{\psi} = \gamma_{a_1 \dots a_n} \psi^i = \Omega_{ik} \psi^k \gamma_{a_1 \dots a_n} \psi^i$

In the $N=1$ case we can convert the pairs of indices i, j into "adjoint indices" $n=0, x=0, 1, 2, 3$ using the Pauli matrices $(\sigma^M)^i_j$ $\sigma^0 = \mathbb{1}_{2 \times 2}$

$$\bar{\psi} \gamma_{a_1 \dots a_n} \sigma^M \psi = (\sigma^M)^i_j \Omega_{jk} \bar{\psi}^i (\gamma_{a_1 \dots a_n})^T C^T \psi^k$$

$\begin{array}{l} \text{symmetric in } ik \quad n=0 \\ \text{antisymmetric in } ik \quad n=x \end{array}$

$\xi = 0$ commuting
 $\xi = 1$ anticommuting

$$(\psi^i T C \gamma_{a_1 \dots a_m} \psi^j)^T = (-1)^\xi \psi^j T C C^{-1} (\gamma_{a_1 \dots a_m})^T C^T \psi^i$$

$$C^T = (i\gamma^0 \gamma^4)^T = i \gamma^{4T} \gamma^{0T} = i \gamma^4 \gamma^0 = -i \gamma^0 \gamma^4 = -C;$$

$$\left. \begin{aligned} \gamma^{0T} &= -\gamma^{0T} = -\gamma^{0-1} = -\gamma^0 \\ \gamma^{4T} &= +\gamma^{4T} = +\gamma^{4-1} = -\gamma^4 \end{aligned} \right\}$$

$$C^{-1} (\gamma_{a_1 \dots a_m})^T C = C^{-1} \gamma_{a_m}^T \dots \gamma_{a_1}^T C = C^{-1} \gamma_{a_m}^T C C^{-1} \gamma_{a_{m-1}}^T \dots =$$

$$= +\gamma_{a_m \dots a_1} = (-1)^{m-1} \cdot (-1)^{m-2} \dots (-1) \gamma_{a_1 \dots a_m} = (-1)^{\lfloor \frac{m}{2} \rfloor} \gamma_{a_1 \dots a_m}$$

$$\bar{\psi}^i \gamma_{a_1 \dots a_m} \psi^j = ()^T = (-1)^{\xi + 1 + \lfloor \frac{m}{2} \rfloor} \bar{\psi}^j \gamma_{a_1 \dots a_m} \psi^i$$

anticommuting spinors even: $m = 0, 1, 4$: odd
 odd: $m = 2, 3$: even commuting spinors

$$\left(\gamma_{a_1 \dots a_m} = \frac{(-1)^{\lfloor m/2 \rfloor}}{(5-m)!} \epsilon_{a_1 \dots a_m b_1 \dots b_{5-m}} \gamma_{b_1 \dots b_{5-m}} \right)$$

Anticommuting spinor bilinears

$$\boxed{\bar{\psi}^i (\sigma^x)^i_j \psi^j, \bar{\psi}^i \gamma_a (\sigma^x)^i_j \psi^j, \bar{\psi}^i \gamma_{ab} \psi^j}$$

(Also $\bar{\psi}^i \gamma_a \psi^j \rightarrow$ fermion etc)

Commuting spinor bilinears

$$\boxed{\bar{\psi}^i \psi^i, \bar{\psi}^i \gamma_a \psi^i; \bar{\psi}^i \gamma_{ab} \sigma^x{}^i_j \psi^j \rightarrow \text{triplets of 2-forms.}}$$

How about the reality? Remember $\bar{\psi}^i$ is really ψ^i_c : $\psi^i_c = \bar{\psi}^i = \psi^{i\dagger}$

$$(\bar{\psi}^i \psi^i)^* \rightarrow (\bar{\psi}^i \psi^i)^{\dagger} = (-1)^\xi \psi^{i\dagger} \psi^i = (-1)^{\xi+1} \psi^{i\dagger} \psi^i =$$

$$= (-1)^{\xi+1} \bar{\psi}^i \psi^i \rightarrow (-1)^{\xi+1} \bar{\psi}^i \psi^i$$

\Rightarrow For commuting spinors $\left\{ \begin{aligned} i \bar{\psi}^i \psi^i &\text{ is real} \\ i \bar{\psi}^i \gamma_a \psi^i &\text{ is real} \\ \bar{\psi}^i \gamma_{ab} \sigma^x{}^i_j \psi^j &\text{ is real} \end{aligned} \right.$

R-symmetry

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For $N=1$ $USp(N) = SO(2)$. If we use a single Dirac spinor we do not see this property. If we introduce $\psi^2 / \psi^{2*} = -\gamma^4 \psi^1$ then we have an $SO(2)$ doublet. All the spinors of the theory (including the supersymmetry transformation parameters) are written in this way and all of them transform simultaneously under $SO(2)$ which is the R-symmetry group.

This is going to be a global symmetry of the theory even after we couple it to supersymmetric matter. This can happen in two ways:

- i) The bosonic fields in the matter multiplets are R-invariant.
- ii) The bosonic fields in the matter multiplets transform in some well-defined way under R-symmetry.

i) \rightarrow Vector and tensor multiplets (which include scalars)

ii) \rightarrow Hypermultiplets (which only include scalars)

For $N > 1$ in $d=5$ ($N > 2$ in $d=4$) the scalars of the theory parametrize homogeneous (symmetric, actually) spaces

$(d=4)$	$N = 3, 4$	$G/H \times G^{matter}/H^{matter}$	H : R-symmetry group
	$N \geq 5$	G/H	$H \subset$ R-symmetry group

In coset spaces there is a natural H (R-) connection & those pullback over the spacetime can couple naturally to the spinors which transform in the same way: scalar-dependent R-symmetry transformations. It is necessary in the covariant derivative of spinors.

$$g = \{ P_a, M_i \}$$

$$-u^{-1} du = e^a P_a + \omega^i M_i$$

$$h = \{ M_i \}$$

$$u(\phi): G/H \text{ coset representative}$$

$$u' = g u h^{-1}(\phi)$$

$$\psi' = \Gamma_{\alpha}^{\beta}(h(\phi)) \psi$$

$$\boxed{\not{D}\psi = \not{\partial}\psi + \omega^i \Gamma_{\alpha}^{\beta}(M_i) \psi}$$

Low - N theories are more flexible: the scalars do not need to live in a fixed coset space (nor in a coset space at all). Then, how is the coupling of the scalars to the spinors made consistent with R-symmetry?

→ The scalar manifolds are required to have the R-symmetry group as a subgroup of the holonomy group.

- Furthermore a specific relation between the curvature and some structures is imposed:

$$N=1, d=4 \left\{ \begin{array}{l} \text{R-symmetry} = U(1) \\ \text{Kähler-Hodge scalar manifolds} \\ (\text{Ricci 2-form} = \text{Kähler 2-form}) \end{array} \right. \left\{ \begin{array}{l} U(1) \subset \text{holonomy} \subset U(m) \\ \text{R related to } \mathcal{F} \\ (\text{to be investigated}) \end{array} \right.$$

$$N=2, d=4 \left\{ \begin{array}{l} \text{R-symmetry} = U(2) = U(1) \times SU(2) \\ \text{Special Kähler scalar manifolds } (\Rightarrow \text{Kähler-Hodge}) \\ \text{Quaternionic-Kähler scalar manifolds } SU(2) \subset \text{holonomy} \\ \oplus \quad R^x = \mathcal{F}^x \quad \text{specific, non-vanishing, constant} \\ (SU(2) \text{ curvature} = \text{hypercomplex structure}) \end{array} \right.$$

$$N=1, d=5 \left\{ \begin{array}{l} \text{R-symmetry} = SU(2) \\ \text{Very special manifolds (R-symmetry neutral)} \\ \text{Quaternionic-Kähler manifolds with same property} \end{array} \right.$$

pullbacks of the

The Kähler connection or the $SU(2)$ component of the spin connection of the Kähler or QK manifolds appears in the covariant derivatives of the spinors.

Now, a global transformation of the scalar manifold (isometry) induces a scalar-dependent transformation of the spinors.

Where do the $R \sim \mathcal{F}$ conditions come from?

I do not really know. Supersymmetry demands them. We can, however, see that those conditions are similar to the properties of the covariant in coset spaces. More important: they are essential for gauging the theories because they play an important rôle in the definition of momentum map.

Supermultiplets

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All supergravities are constructed by coupling a supermultiplet that contains the metric (vielbein e^a_μ) and its supersymmetric partners (gravitinos ψ^i) plus other fields, called "supergravity multiplet", to matter supermultiplets (if they exist). The theory are constructed from the supergravity multiplet is invariant under supersymmetry transformations by itself and it is called "pure supergravity".

The matter supermultiplets may be used to construct consistent theories on a fixed background by themselves, but we will not go into this problem.

The supermultiplets of $N=1, d=5$ supergravity are:

$$\text{Supergravity multiplet} : \{ e^a_\mu, \psi^i, A_\mu \} \quad \begin{array}{l} A_\mu : \text{graviphoton} \\ \psi^i : (SM) \text{ gravitino} \end{array}$$

$$\text{Vector supermultiplet} : \{ A_\mu, \lambda^i, \phi \} \quad \lambda^i : (SM) \text{ gaugino}$$

$$\text{Tensor supermultiplets} : \{ B_{\mu\nu}, \lambda^i, \phi \} \quad (\text{dual to vectors})$$

$$\text{Hypermultiplets} \quad \{ q^X, \Sigma^A \} \quad X=1, \dots, 4, \quad A=1, 2 \rightarrow SU(2)$$

We are not going to consider tensor multiplets in most of what we are going to do. Some results still have to be generalized to include them properly. In many cases they can be replaced by vector multiplets, but not always.

In general we will have more than one vector multiplet or hypermultiplet. First, we need to adapt our notation to this possibility:

$$\{ A^x_\mu, \lambda^{xi}, \phi^x \} \quad x=1, \dots, m_V$$
$$(A_\mu^I) = (A_\mu^0, A_\mu^x); \quad A_\mu^0 = A_\mu; \quad \{ q^X, \Sigma^A \} \quad X=1 \dots 4m_H; \quad A=1 \dots 2m_H$$

Second, we have to study the possible couplings of these fields.

Real Special Geometry

miércoles, 30 de noviembre de 2016 18:42

In general the scalar fields of a supergravity theory parametrise some space with a non-trivial metric and their kinetic terms are a σ -model.

Furthermore, they may couple to other fields through functions with special properties: kinetic matrices etc.

For the scalar fields in the vector multiplets ϕ^x all these structures are integrated into "Real Special Geometry".

The n_V -dimensional space parametrised by these scalars can always be seen as a codimension-1 hypersurface in a (n_V+1) -dimensional space with coordinates h^I , $I=0, \dots, n_V$ (same labels as the vector fields) defined by an equation of the form $C_{IJK} h^I h^J h^K = 1$.

There are linear and non-linear symmetries of this hypersurface.

The former are the linear symmetries of the symmetric tensor C_{IJK} and they are the only ones that can be symmetries of the whole theory (the vectors A^I_μ must transform linearly).

These symmetries (if any) act non-linearly on the physical scalar fields that solve the equation $h^I(\phi)$.

Some definitions: $h_I \equiv C_{IJK} h^J h^K$ (covariant)

$$\Rightarrow h_I h^I = 1;$$

$$a_{IJ} \equiv -2 C_{IJK} h^K + 3 h_I h_J;$$

$$\Rightarrow a_{IJ} h^J = h_I; a^{IJ} h_J = h^I \text{ etc.}$$

a_{IJ} is the metric on the embedding space $dS^2 = h_{IJ} dh^I dh^J$

It will play the role of kinetic matrix for the vector fields and has the same symmetries as C_{IJK} (linear)

The induced metric on the hypersurface $g_{xy} = 3 a_{IJ} \partial_x h^I \partial_y h^J$ is the metric of the σ -model. $h_I \partial_x h^I = h^I \partial_x h_I = 0$

$$A^I = (h_I A^J) h^I - 3 (\partial_x h_I A^I) g^{xy} \partial_y h^I \text{ etc.}$$

$\Rightarrow h_{\pm}$ can be used to project onto the graviphoton sector.

$\partial_x^{\pm} (\sim h_x^{\pm})$ can be used to project onto the matter sector.

From the supersymmetry point of view, these are not $A_{\mu}^{\circ} A_{\mu}^{\times}$, but the combinations that occur in the gravitino and gaugino supersymmetry transformation rules.

So far we know 2 terms of the bosonic action

σ -model

$$\frac{1}{2} g_{xy} g^{\mu\nu} \partial_{\mu} \phi^x \partial_{\nu} \phi^y ;$$

vectors

$$-\frac{1}{4} a_{\pm\pm} g^{\mu\nu} g^{\rho\sigma} F_{\mu\nu}^{\pm} F_{\rho\sigma}^{\pm} ;$$

Hypers and QK manifolds

sábado, 3 de diciembre de 2016 21:23

The scalars in the hypermultiplets parametrize a quaternionic-Kähler manifold of dimension $4m_H$. They are defined as follows:

- i) They are endowed with a triplet of complex structures \mathcal{I}^r_{XY}
 $X, Y = 1, \dots, 4m_H; r, s, t = 1, 2, 3$
 $\mathcal{I}^r_{XY} \mathcal{I}^s_{YZ} = -\delta_{XZ} \quad ((\mathcal{I}^r)^2 = -1)$
- ii) The triplet satisfies the algebra of imaginary quaternions
 $\mathcal{I}^x \mathcal{I}^y = -\delta^{xy} + \epsilon^{xyz} \mathcal{I}^z$
- iii) The Riemannian metric g_{XY} is Hermitian w.r.t. the three complex structures
 $\mathcal{I}^r_{XZ} \mathcal{I}^r_{YZ} = g_{XY} \quad g_{ZW} = g_{XZ} \mathcal{I}^r_{YW} \quad r=1,2,3$
 $\Rightarrow 3$ Kähler 2-forms $K^r_{XY} = \mathcal{I}^r_{XZ} g_{ZY}$
- iv) There is an $SU(2)$ bundle over the QK manifold with a connection 1-form $A^r_X dg^X$ and the $L(G + SU(2))$ covariant derivative of the K^r 's is zero:
 $D_X K^r_{YZ} = \nabla_X K^r_{YZ} + \epsilon^{rst} A^s_X K^t_{YZ} = 0$
- v) The curvature of the $SU(2)$ connection F^r_{XY} is proportional to the Kähler 2-forms \mathcal{I}^r_{XY}

$$K^r_{XY} = \kappa \mathcal{I}^r_{XY} ; \quad \begin{cases} \kappa = 0 \Rightarrow \text{hyper-Kähler} \\ \kappa \neq 0 \Rightarrow \text{quaternionic-Kähler} \end{cases}$$

In supergravity $N=1, d=5$ supergravity $\boxed{\kappa = -1}$

QK manifolds have special holonomy:

$$SU(2) \times Sp(2m_H) \subset SO(4m_H)$$

$$2 \times (4m_H^2 - 1) \quad 2m_H(4m_H - 1) = 8m_H^2 - 2m_H$$

The tangent-space indices can be represented by pairs iA
 Vierbein \rightarrow "Quadbein" f^i_A $\xrightarrow{SU(2)}$ iA $\xleftarrow{Sp(2m_H)}$

Given a $\mathcal{N}=1$ multiplet of dimension $4n_H$, the kinetic term of the hyperscalars is the σ -model

$$\frac{1}{2} g_{XY} g^{\mu\nu} \partial_\mu q^X \partial_\nu q^Y$$

There are no more couplings of the hypers to the rest of the fields: the structure of the theory does not allow it. Only when we gauge global symmetries some couplings will appear because we will have to use vectors from the vector multiplets. If the symmetries being gauged act on the hypers, there will be couplings between these two kinds of multiplets.

The ungauged theory

miércoles, 30 de noviembre de 2016 18:42

We have all the elements we need to describe the simplest $N=1, d=5$ supergravity theories in which no global symmetry has been gauged. We are interested in the bosonic action only ($\psi^{\pm}=0$) since it is enough to get the equations of motion of the bosonic fields ($\psi^{\pm}=0$ is a "consistent truncation"). We want the supersymmetry transformation rules of the fermions for vanishing fermions ($\psi^{\pm}=0$) because they will become the KSEs. Finally, we want the complete supersymmetry transformation rules of the bosons (setting $\psi^{\pm}=0$ would trivialize them) because we want to use them to find the KSI's.

The action contains the elements mentioned before plus an Einstein-Hilbert term and a Chern-Simons term for the vector fields which is very characteristic of these theories:

$$S = \int d^5x \sqrt{|g|} \left\{ R + \frac{1}{2} g_{\mu\nu} \partial_{\mu} \phi^{\pm} \partial^{\nu} \phi^{\pm} + \frac{1}{2} g_{\mu\nu} \partial_{\mu} q^X \partial^{\nu} q^Y \right. \\ \left. - \frac{1}{4} a_{IJ} F^I - \bar{F}^J + \frac{1}{12\sqrt{3}} C_{IJK} \frac{\epsilon^{\mu\nu\sigma\rho} \delta^I_{\mu} \bar{F}^J_{\nu} F^K_{\sigma\rho}}{\sqrt{|g|}} A^K \right\}$$

supersymmetry.

The supersymmetry transformation rules of the fermions for vanishing fermions are

$$\delta_{\epsilon} \psi_{\mu}^i = \nabla_{\mu} \epsilon^i - \frac{1}{8\sqrt{3}} h_{\mathbb{I}} F^{\mathbb{I}\alpha\beta} (\gamma_{\mu\alpha\beta} - 4 g_{\mu\alpha} \gamma_{\beta}) \epsilon^i; \rightarrow \text{Differential}$$

$$\left. \begin{array}{l} \delta_{\epsilon} \lambda^{ix} = \frac{1}{4} (\not{\partial} \phi^{\pm} - \frac{1}{2} h^x_{\mathbb{I}} \not{F}^{\mathbb{I}}) \epsilon^i; \\ \delta_{\epsilon} \xi^A = \frac{1}{2} f^A_x \not{\partial} q^X \epsilon^i; \end{array} \right\} \begin{array}{l} \text{algebraic} \\ \text{constraints} \end{array}$$

matter vector fields R-symmetry

(We could use $f^A_x \epsilon^i$)

All the symmetries of the theory act covariantly on both sides of the equations.

In absence of hyper, $D_{\mu} \rightarrow \nabla_{\mu}$ (Levi-Civita only)

The supersymmetry transformation rules of the bosons are always algebraic and, furthermore, do not change when we gauge the theory:

$$\delta_\epsilon e^a_\mu = \frac{i}{2} \bar{\epsilon}_i \gamma^a \psi_\mu^i;$$

$$\delta_\epsilon A^I_\mu = -i \frac{\sqrt{3}}{2} h^I \bar{\epsilon}_i \psi_\mu^i + \frac{i}{2} h^I_x \bar{\epsilon}_i \gamma_\mu \lambda^{xi};$$

$$\delta_\epsilon \phi^x = \frac{i}{2} \bar{\epsilon}_i \lambda^{xi};$$

$$\delta_\epsilon q^x = -i \left(f^x_{iA} \bar{\epsilon}^i \right) \sum^A \rightarrow \text{the combination that we could have used before } \sum^x_i;$$

Examples of ungauged $N=1, d=5$ supergravities

i) Pure supergravity $m_V = m_H = 0$ & $C_{000} = 1$ (simplicity)
 $h^0 = 1$; $a_{00} = 1$;

Suppressing the index "0"

$$S = \int d^5 x \sqrt{|g|} \left\{ R - \frac{1}{4} F^2 + \frac{1}{12\sqrt{3}} \frac{\epsilon^{\mu\nu\rho\sigma}}{\sqrt{g}} \bar{T}_\mu T_\nu T_\rho T_\sigma \Delta S \right\}$$

\rightarrow Einstein-Maxwell + a particular Chern-Simons term.

$$\begin{cases} \delta_\epsilon e^a_\mu = \frac{i}{2} \bar{\epsilon}_i \gamma^a \psi_\mu^i; \\ \delta_\epsilon \psi_\mu^i = \frac{1}{\sqrt{g}} \bar{\epsilon}_i - \frac{1}{2\sqrt{3}} F^{\alpha\beta} (\gamma_{\mu\alpha\beta} - 4g_{\mu\alpha} \gamma_\beta) \epsilon^i; \\ \delta_\epsilon A_\mu = -i \frac{\sqrt{3}}{2} \bar{\epsilon}_i \psi_\mu^i; \end{cases}$$

ii) ST[2, m_V] models (strictly speaking, it is the $N=2, d=4$ models that are obtained from them by dimensional reduction that are called this way).

They have $m_H = 0$ and are defined by $C_{0xy} = \frac{1}{2!} \eta_{xy}$;

$$(\eta_{xy}) = \text{diag} (+ - - \dots -)$$

$$C_{IJK} h^I h^J h^K = \frac{1}{2} h^0 \eta_{xy} h^x h^y = 1;$$

We can solve this constraint in this way:

3

\gg Only $SO(1,1) \times SO(1, m_V - 1)$ is linearly realized, \ll though!

domingo, 4 de diciembre de 2016

18:18

The $\eta_{xy} h^\mu h^\nu$ part is invariant under $SO(1, m_V - 1)$ transformations, but, together with the conformal factor $\frac{1}{2} h^0$, the symmetry is the conformal group of the metric $\eta_{\lambda\sigma} : SO(2, m_V - 1)$. Since the dimension of the hypersurface is m_V , this model describes the coset space

$$SO(2, m_V - 1) / SO(1, m_V - 1) \rightarrow \frac{(m_V + 1)m_V}{2} - \frac{m_V(m_V - 1)}{2} = m_V \quad \boxed{AdS_{m_V}}$$

$$\left(\begin{array}{l} (X^0)^2 + \eta_{xy} X^x X^y = 1; \\ (X^0)^2 + (X^1)^2 = \frac{1}{2} h^0 (h^1)^2; \quad X^2 = \left(\frac{h^0}{2}\right)^{1/2} h^2 \dots \\ \Rightarrow \frac{1}{2} h^0 \eta_{xy} h^x h^y = 1 \end{array} \right)$$

We can use all the parameterizations of AdS_{m_V} to find $h^\mu(\phi)$.

Using the definitions $h_I \equiv C_{IJK} h^J h^K$:

$$a_{I\bar{J}} \equiv -2 C_{I\bar{J}K} h^K + 3 h_I h_{\bar{J}}$$

$$\Rightarrow h_0 = \frac{1}{3!} \eta_{xy} h^x h^y = (3h^0)^{-1}; \quad h_x = \frac{1}{3} \eta_{xy} h^0 h^y;$$

$$h_I h^{\bar{I}} = h_0 h^0 + h_x h^x = \frac{1}{3} + \frac{1}{3} h^0 \eta_{xy} h^x h^y = \frac{1}{3} + \frac{2}{3} = 1;$$

$$a_{00} = 3 h_0 h_0 = \frac{1}{3(h^0)^2}$$

$$a_{0x} = -2 \frac{1}{3!} \eta_{xy} h^y + 3 h_0 h_x = -\frac{1}{3} \eta_{xy} h^y + \frac{1}{h^0} \frac{1}{3} \eta_{xy} h^0 h^y = 0$$

$$\begin{aligned} a_{xy} &= -2 \frac{1}{3!} \eta_{xy} h^0 + 3 \left(\frac{1}{3!} \eta_{xz} h^z \eta_{yw} h^w \right) (h^0)^2 = \\ &= -\frac{1}{3} \left[\eta_{xy} h^0 + (h^0)^2 \eta_{xz} \eta_{yw} h^z h^w \right]; \end{aligned}$$

The σ -model metric is just that of $SO(1,1) \times SO(1, m_V - 1)$

The Chern-Simons term is

$$\left(\frac{\epsilon}{24\sqrt{3}} \right) C_{IJK} F^I F^J A^K = \frac{1}{2!} \left(2 \underbrace{F^0 \eta_{\lambda\sigma} F^\lambda A^\sigma}_{2\partial(A^0 \eta_{\lambda\sigma} F^\lambda A^\sigma)} + \eta_{\lambda\sigma} F^\lambda F^\sigma A^0 \right)$$

$$\Rightarrow \boxed{\frac{1}{24\sqrt{3}} \frac{\epsilon^{\mu\nu\sigma\delta}}{\sqrt{|g|}} \eta_{\lambda\sigma} F^\lambda F^\sigma A^0}$$

STU model $m_H = 0$; $m_V = 2$; $C_{IJK} = \frac{1}{3!} |\varepsilon_{IJK}|$ $\boxed{h^0 h^1 h^2 = 1}$
 The symmetry of this model is $SO(1,1)^3$ with each factor acting on a pair $h^0 h^1$, $h^0 h^2$, $h^1 h^2$ by rescaling with opposite weights.

$$h_I = \frac{1}{3 h^I} ; \quad a_{I3} = 3 \delta_I(3) h^{(3)^2} ;$$

A convenient parameterization with reduced metric $g_{xy} = \delta_{xy}$ is

$$h^0 = e^{\sqrt{6}\phi^1} ; \quad h^1 = e^{-\sqrt{\frac{3}{2}}\phi^1 - \frac{3}{\sqrt{2}}\phi^2} ; \quad h^2 = e^{-\sqrt{\frac{3}{2}}\phi^1 + \frac{3}{\sqrt{2}}\phi^2} ;$$

$$S = \int d^5x \sqrt{|g|} \left\{ R + \frac{1}{2} \partial_\mu \phi^x \partial^\mu \phi^x - \frac{1}{12} e^{-2\sqrt{6}\phi^1} (F^0)^2 - \frac{1}{12} e^{\sqrt{6}\phi^1 + 3\sqrt{2}\phi^2} (F^1)^2 - \frac{1}{12} e^{\sqrt{6}\phi^1 - 3\sqrt{2}\phi^2} (F^2)^2 + \frac{1}{12\sqrt{3}} \frac{\varepsilon}{\sqrt{g}} F^0 F^1 \Delta^2 \right\}$$

Observe that the $ST[2,2]$ model, which parameterizes $SO(1,1) \times SO(1,1)$ related to the STU model:

$$\frac{1}{2} h^0 [(h^1)^2 - (h^2)^2] = h^0 \frac{h^1}{\sqrt{2}} \frac{h^1}{\sqrt{2}} - \frac{h^2}{\sqrt{2}} \frac{h^2}{\sqrt{2}}$$

They are the same model in a different basis.

Global symmetries

miércoles, 30 de noviembre de 2016 18:43

Is it possible to construct other theories of $N=1, d=5$ supergravity? There are only two possibilities which can be understood as deformations of a given ungauged theory (\Rightarrow same # of d.o.f.)

1.- Motivic deformations: we can try to introduce a Stückelberg-type coupling between 2-forms and 1-forms (in general $(k+1)$ - to k -forms)

$$F = dA \longrightarrow dA + mB \quad A=0 \Rightarrow \text{massive 2-forms consistently with eq.}$$
$$H = dB$$

Since we are not including 2-forms in the theory, we are not going to explore this possibility.

2.- Gaugings of global symmetries of the ungauged theory: we modify the couplings so that the theory becomes invariant under the local version of a global symmetry. Since we need connection 1-forms, this can only be done when the theory already has vector multiplets that can play that role.

Which are the global symmetries of an $N=1, d=5$ supergravity?

i) $SU(2)$ R-symmetry acting only on the SM spinors.

* However, in presence of hypers they are coupled to the spinors via the pullback of the $SU(2)$ connection $A_{\mu}^x \rho_{\mu}^x$ that occurs in the $SU(2)$ -covariant derivative. Thus, we must do something to the hypers to compensate for this transformation. That "something" must leave invariant the QK metric g_{xy} and so it must be an isometry. But it must leave the whole QK structure invariant as well. In particular, it must preserve the hyper-Kähler structure $\mathcal{I}^2 \Rightarrow$ it must be a tri-holomorphic isometry.

Thus, in presence of hypers, R-symmetry is no longer an independent symmetry: it is part of the group of tri-holomorphic

- isometries of the QK manifold. We will discuss this point later.
- ii) Isometries of the scalar manifolds that leave invariant the whole theory. This requires the preservation of all the geometric structures required by supersymmetry (Real Special Geometry and QK Geometry) and also the couplings to the rest of the fields. In the QK case we have already said something but we are going to discuss the question in more detail now.

Global symmetries associated to biholomorphic isometries of the QK manifold

The scheme of how they work is the following (no mathematical rigour)

① We transform the hypers $\delta q^x = \alpha^A k_A^x(q)$ α^A constants
 $[k_a, k_b] = -f_{ab}^c k_c$;

② If the $k_A^x(q)$ are Killing vectors of g_{xy} ; $\mathcal{L}_{k_a} g_{xy} = 0$ and the kinetic term is left invariant.

③ If $\mathcal{L}_{k_a} \mathcal{F}^2 = 0$; $a=1,2,3$, the QK structure is preserved ???

* This statement is not $SU(2)$ -covariant. It must be replaced

by $\mathbb{L}_{k_a} K^1 = 0$ where \mathbb{L}_{k_a} is the $SU(2)$ -covariant Lie

derivative $\mathbb{L}_{k_a} K_{xy}^2 = \mathcal{L}_{k_a} K_{xy}^2 - \varepsilon^{rst} W_A^s K_{xy}^t$

W_A^s is the compensator

$$W_A^s \equiv k_A^x A_x^s - P_A^s \quad \leftarrow \text{definition of the biholomorphic invariant map.}$$

W_A^s undergoes a compensating $SU(2)$ transformation when we perform the scalar transformation corresponding to the isometry generated by k_a . But it does not transform covariantly (P_A^s does (the inhomogeneous term is absorbed by $k_a^x A_x^s$)).

Remember: this is similar to the Lorentz case (Kosmann derivative)

$$\text{where } W_A^{ab} = k_A^{\mu} \omega_{\mu}^{ab} - \underbrace{\nabla_{\mu} k_A^{\nu}}_A \rightarrow \text{"invariant map"}$$

$$\left. \begin{array}{l} \perp_{k_A} K^2_{xy} = 0; \\ \oplus \\ D_2 K^2_{xy} = 0; \end{array} \right\} -2 \left(\nabla_{[X} k_A^Z \right) K^2_{ZY]} + \epsilon^{1st} P_A^S K^t_{xy} = 0;$$

Contracting with $K^2_{xy} \rightarrow K^2_{xy} \nabla_x k_{Ay} = -2m_H P_A^x$;

Acting on both sides with $D_2 \rightarrow K^2_{xy} D_2 \nabla_x k_{Ay} = -2m_H D_2 P_A^x$;

Using the integrability condition for Killing vectors $\rightarrow K^1_{xy} (-R^W_{zxy} k_{AW}) = -2m_H D_2 P_A^x$

$$D_2 P_A^x = \frac{1}{2m_H} k_A^W \underbrace{R_{Wzxy}}_{-2m_H F^z_{Wz}} K^1_{xy}$$

$$\Rightarrow \boxed{D_2 P_A^x = \kappa K^2_{zW} k_A^W}$$

This is the usual definition of the bi-holomorphic invariant.

However, remember the previous equation

$$\boxed{D_2 P_A^x = \frac{1}{2m_H} k_A^W R_{Wzxy} K^1_{xy}}$$

because we can show how this structure occurs in more general contexts where there are no complex structures involved
 \rightarrow Generalized concept of momentum map.

Generalized momentum maps

lunes, 5 de diciembre de 2016 0:56

Given a Riemannian (or pseudo Riemannian, the signature plays no rôle here) manifold M_d admitting an isometry group generated by the Killing vectors k_A^a : $\nabla_a k_{AB} = \nabla_{[a} k_{A|B]}$ we define the generalized momentum map associated to the Levi-Civita connection ω_μ^{ab} and the Killing vectors k_A^a by

$$\boxed{P_A^a \equiv \nabla^a k_A^b = -\nabla_b k_A^a} \in \mathfrak{so}(d)$$

Properties:

- i) It associates an infinitesimal isometry on the base space k_A^a to an infinitesimal rotation in the target space.
- ii) The Komar Lie derivative on an object T transforming in the representation \mathfrak{r} of the rotation group is given by

$$\mathcal{L}_{k_A} = \mathcal{L}_{k_A} - \frac{1}{4} \left(k_A^M \omega_\mu^{ab} - 2 P_A^{ab} \right) \Gamma_\mu^{\mathfrak{r}}(M_{ab})$$

- iii) If M has special holonomy generated by some $(M_i)^a \in \mathfrak{so}(d)$

$$\text{we can reduce } P_A^a \equiv P_A^i \Gamma_\mu^{\mathfrak{r}}(M_i)^a; \quad [M_i, M_j] = -f_{ij}^k M_k$$

$$\omega_\mu^{ab} = -\theta_\mu^i \Gamma_\mu^{\mathfrak{r}}(M_i)^a;$$

$$R_{\mu\nu}{}^{ab} = -R_{\mu\nu}{}^i(\theta) \Gamma_\mu^{\mathfrak{r}}(M_i)^a;$$

and using the integrability conditions for Killing vectors

$$\nabla_a \nabla_b k_A^c = k_A^d R_{dab}{}^c \rightarrow \nabla_a P_A^c \equiv k_A^d R_{dab}{}^c$$

and reducing it to the holonomy group becomes

$$\boxed{D_a P_A^i = R_{ab}{}^i(\theta) k_A^b} \quad (D_a P_A^i = \partial_a P_A^i + f_{jk}^i \theta_a^j P_A^k)$$

which is the general form of the equation that defines the momentum map. \Rightarrow Defined up to covariantly-constant pieces: FI terms

i) If M is a Riemannian symmetric space G/H ; $u^i = g a^i h^{-1}$ the coset rep.

$$g \equiv 1 + \alpha^A T_A;$$

$$h \equiv 1 - \alpha^A W_A^i M_i;$$

$$x^{\mu'} \equiv x^\mu + \alpha^A k_A^\mu;$$

$$\{T_A\} = \{P_a, M_i\} \quad A = a, i.$$

$$-u^i du = e^a T_a + \omega^i M_i;$$

It can be easily shown that

$$k_A^a = -F_{ab} (u^i)^a A^b;$$

$$W_A^i = -k_A^\mu \omega_\mu^i - T_A^i; \quad \text{with } T_A^i = F_{ab} (u^i)^a A^b;$$

P_A transforms as

$$\boxed{P_B^i \left(\frac{\partial x^{\mu'}}{\partial x^\mu} \right)^j_A = F_{ab} (h)^i_j P_A^j;}$$

and satisfies the equation that defines the momentum map.

ii) If M is a Kähler-Hodge manifold $R_{\mu\nu}$ is related to $K_{\mu\nu}$
 $R_{\mu\nu} \rightarrow$ Ricci 2-form $R_{\mu\nu} = \frac{1}{2} R_{\mu\nu\sigma\rho} \mathcal{I}^{\sigma\rho}$; where $\mathcal{I}^{\sigma\rho}$
 $K_{\mu\nu} \rightarrow$ Kähler 2-form $K_{\mu\nu} = g_{\mu\sigma} \mathcal{I}^{\sigma\nu}$; is the complex structure

The part of the holonomy group which is relevant for us is the $U(1)$ of $R_{\mu\nu}$. In general $P_A^a \notin \mathfrak{u}(1)$ and we are going to be interested only on those isometries for which $P_A^a \in \mathfrak{u}(1)$.

These are the holomorphic isometries. We are going to show that they satisfy the equation that defines the momentum map for the $u(1)$ subgroup.

Holomorphic isometries preserve the Kähler 2-form (covariantly constant by def)

$$0 = \mathcal{L}_{k_A} K_{ab} = k_A^c \cancel{\nabla_c K_{ab}} + 2 \nabla_{[a} k_A^c K_{c]b} =$$

$$= 2 \nabla_{[a} (k_A^c K_{c]b}) + 2 k_A^c \cancel{\nabla_{[a} K_{c]b}}$$

$$\Rightarrow k_A^c K_{cb} = \partial_a f_A \quad \text{locally}$$

$$\partial_a f_A = -K_{ac} k_A^b \sim -R_{ab} k_A^b = -\frac{1}{2} R_{abcd} \mathcal{I}^{cd} k_A^b$$

$$\Rightarrow f_A \sim P_A \quad \text{for } u(1) \text{ only}$$

relation to be investigated.

To be improved

vi) For QK manifolds we have already seen how it works.
 KH & QK are essential. just K or hK does not work!

Gauging isometries

lunes, 5 de diciembre de 2016 0:21

The procedure to gauge a global symmetry of a theory which acts on the fields according to

- i) Scalars $\delta_\alpha \phi^x = \alpha^A k_A^x(\phi)$; $[k_A, k_B] = -f_{AB}^C k_C$;
 k_A^x Killing vectors of the scalar manifold respecting all the structures demanded by supersymmetry.
- ii) Vectors $\delta_\alpha A_\mu^I = \alpha^A (T_A)^I_{\ J} A_\mu^J$ where the $T_A^I_{\ J}$ are in the adjoint representation of the group that we want to gauge. Since not all the vectors transform, it is customary to write $\alpha \rightarrow \alpha^I$ and $(T_A)^K_{\ J} \rightarrow f_{IJ}^K$: $\delta_\alpha \phi^x = \alpha^I k_I^x(\phi)$; $[k_I, k_J] = -f_{IJ}^K k_K$;
 $k_A \rightarrow k_I$ (some vanishing) $\delta_\alpha A_\mu^I = \alpha^J f_{JK}^I A_\mu^K$;
- iii) Spinors: we must distinguish between isometries of the RS and QK manifolds because the spinors only feel the transformations associated to the latter:

$$\begin{cases} \delta_\alpha \phi^x = \alpha^I k_I^x(\phi); & [k_I, k_J] = -f_{IJ}^K k_K; \\ \delta_\alpha q^X = \alpha^I K_I^X(q); & [K_I, K_J] = -f_{IJ}^K K_K; \\ \delta_\alpha A_\mu^I = \alpha^J f_{JK}^I A_\mu^K; \end{cases}$$

same algebras because A_μ^x, ϕ^x are in the same multiplet and $A_\mu^I, k^I(\phi)$ must transform in the same way.

If the $K_I^X \neq 0$, then $\delta_\alpha \psi^i = \alpha^I \underbrace{\left(K_I^X A_X^{\ J} + P_I^{\ J} \right)}_{\text{conformal } W_A^{\ J}} \frac{i}{2} (\sigma^2)^i_{\ j} \psi^j$

$$\left. \begin{aligned} D_\mu \psi^i &= \nabla_\mu \psi^i + A_\mu^X \partial_\mu q^X \frac{i}{2} (\sigma^2)^i_{\ j} \psi^j; \\ \delta_\alpha \psi^i &= \alpha^I W_I^{\ J} \frac{i}{2} (\sigma^2)^i_{\ j} \psi^j; \end{aligned} \right\} \text{only covariant under global transformations: } \alpha^i \text{ constant}$$

induced $SU(2)$ transformations.

goes as follows:

a) Replace derivatives by gauge-covariant derivatives

$$\partial_\mu \phi^x \rightarrow \mathcal{D}_\mu \phi^x = \partial_\mu \phi^x + g A_\mu^I k_I^x(\phi);$$

$$\partial_\mu q^X \rightarrow \mathcal{D}_\mu q^X = \partial_\mu q^X + g A_\mu^I K_I^X(q);$$

$$D_\mu \psi^i \rightarrow \mathcal{D}_\mu \psi^i = \underbrace{D_\mu \psi^i}_{\text{Lorentz}} + g A_\mu^I P_I^{\ J} \frac{i}{2} (\sigma^2)^i_{\ j} \psi^j;$$

$$k_I^x A_x^2 - W_I^2$$

Observe that

$$\begin{aligned} \mathcal{D}_\mu \psi^i &= \nabla_\mu \psi^i + (A^2 \times \partial_\mu q^x + g A_\mu^I \tilde{T}_I^2) i(\sigma^2)_j^i \psi^j \\ &= \nabla_\mu \psi^i + [A^2 \times (\partial_\mu q^x + g A_\mu^I k_I^x) - g W_I^2] i(\sigma^2)_j^i \psi^j \\ &= \nabla_\mu \psi^i + (A^2 \times \mathcal{D}_\mu q^x - g W_I^2) i(\sigma^2)_j^i \psi^j \end{aligned}$$

⇒ To obtain the gauge-covariant derivative it is not enough to replace the pullback of the $SO(2)$ connection by the "covariant pullback" if $W_I^2 \neq 0$ (which is usually the case)

Observe that on the RS manifold, the preservation of the RS structure by the isometries amounts $T_A^L (C_{JK})_L = 0 \Rightarrow \int_M \epsilon^L (C_{JK})_L = 0$ and $\mathbb{L}_A h^I = \mathcal{L}_{k_A} h^I - (T_A)^I_J h^J = k_A^x \partial_x h^I - (T_A)^I_J h^J = 0$

$$\Rightarrow k_A^x = -\sqrt{3} T_A^I \partial_I h^x h^I ; \quad \boxed{k_I^x = -\sqrt{3} \int_{JK} h^J h^K}$$

⇒ They vanish for Abelian isometry groups. They cannot be gauged alone!

b) Replace the vector field strengths by covariant field strengths

$$F^I = dA^I \longrightarrow dA^I + g \int_{JK}^I A^J \wedge A^K$$

c) The Chern-Simons term has to be modified to make it gauge-invariant (up to total derivatives)

$$\frac{1}{12\sqrt{3}} \frac{\epsilon}{\sqrt{|g|}} C_{JKL} F^I F^J A^K \longrightarrow \frac{1}{12\sqrt{3}} \frac{\epsilon}{\sqrt{|g|}} C_{JKL} \left\{ F^I F^J A^K - \frac{1}{2} g \int_{LM}^I F^J A^K \wedge A^L \wedge A^M + \frac{1}{10} g^2 \int_{LMN}^I \int_{NP}^J A^K \wedge A^L \wedge A^M \wedge A^N \wedge A^P \right\}$$

d) The closure of the local supersymmetry algebra requires the modification of the supersymmetry transformation rules of the fermions. Apart from the replacement of derivatives and field strengths by their covariant counterparts, new terms named "fermion shifts" have to be added.

They are generically related to the inhomogeneous membrane ansatz:

$$\delta_\epsilon \psi_\mu^i = \mathcal{D}_\mu \epsilon^i - \frac{1}{8\sqrt{3}} h_I^x F^{I\alpha\beta} (\gamma_{\mu\alpha\rho} - 4 g_{\mu\alpha} \delta_\rho) \epsilon^i + \frac{1}{2\sqrt{3}} g h^I \tilde{T}_{Ij}^i \gamma_\mu \epsilon^j ;$$

$$\delta_\epsilon \lambda^{ix} = \frac{1}{2} (\not{\partial} \phi^x - \frac{1}{2} h^x \not{F}^I) \epsilon^i + g h^{Ix} \tilde{T}_{Ij}^i \epsilon^j ;$$

Different basis! $\rightarrow \delta_\epsilon \zeta^A = \frac{1}{2} \not{x}^{iA} (\not{\partial} q^x + \sqrt{3} g h^I K_I^x) \epsilon^i ;$

These new terms, in their turn, generate new terms in the variation of the action that need to be compensated by the introduction of a scalar potential:

$$V(\phi, g) = -g^2 \left\{ \left(4h^{\bar{I}\bar{I}} - 2g^{xy} h_x^{\bar{I}} h_y^{\bar{I}} \right) \bar{P}_{\bar{I}}^{\bar{I}} \bar{P}_{\bar{I}}^{\bar{I}} \right. \\ \left. - \frac{3}{2} h^{\bar{I}\bar{J}} h^{\bar{K}\bar{L}} \left(k_{\bar{I}\bar{K}}^x k_{\bar{J}\bar{L}}^y g_{xy} + k_{\bar{I}\bar{L}}^x k_{\bar{J}\bar{K}}^y g_{xy} \right) \right\}$$

$$k_{\bar{I}\bar{K}}^x h^{\bar{I}\bar{K}} \sim \int_{\bar{I}\bar{J}} k^{\bar{I}\bar{K}} h^{\bar{J}\bar{L}} h_{\bar{K}\bar{L}}^x h^{\bar{I}\bar{J}} = 0.$$

\Rightarrow The scalar potential vanishes if $m_H = 0$. ($\bar{P}_{\bar{I}}^{\bar{I}} = 0$)

However, it is possible to have $\bar{P}_{\bar{I}}^{\bar{I}} \neq 0$ for $m_H = 0$! (Tayet-Gloppoulos terms)

Fayet-Iliopoulos terms

miércoles, 30 de noviembre de 2016 18:43

If $m_H = 0$ one can still find P_I^a 's which are constant and satisfy the basic properties needed. They are called Fayet-Iliopoulos terms and come in two flavors:

$U(1)$: $P_I^a = \text{constant}$ for 1 value of I and one value of a (chosen at will because these transformations only affect the spinors (it is a $U(1)$ subgroup of the $SU(2)$ R-symmetry group). Using it, we gauge that $U(1) \subset SU(2)$ R-symmetry group.

$SU(2)$ $P_I^a = 0$ possible vectors \vec{e}_a satisfies $\vec{e}_1 \times \vec{e}_2 = \epsilon_{123} \vec{e}_3$ ($\vec{I} \rightarrow \vec{a}$). In this case $SU(2)$ acts on the coordinates of the RSG because the vectors have to transform in the adjoint of $SU(2)$ in order to be used as gauge fields (connections)

In these cases the scalar potential becomes

$$U(1): V = -g^2 [4(h^*)^2 - 2g^2 \partial_x h^* \partial_y h^*] \leftarrow \text{not definite}$$

$$SU(2) V = -g^2 [4|h^|^2 - 2g^2 \partial_x h^i \partial_y h^i] \leftarrow \text{(using the simplest choice)}$$

We can use FI term to gauge $U(1)$ in pure $d=5$ supergravity because it already has one vector (the graviphoton): $V = -4g^2 < 0 \Rightarrow$ AdS-like
This theory is called "minimal gauged $d=5$ supergravity".

Relations with other SUGRAs via redox

miércoles, 30 de noviembre de 2016 18:45

- $d=11$ supergravity ("M-theory"), compactified on a Calabi-Yau 3-fold with Hodge numbers $h_{(1,1)}, h_{(2,1)}$ and with triple interaction numbers C_{IJK} , $I, J, K = 0, \dots, h_{(1,1)} - 1$, becomes an $N=1, d=5$ supergravity with $h_{(1,1)} - 1 = m_V$ vector multiplets and $h_{(2,1)} + 1 = m_H$ hypermultiplets.
- Further reduction to $d=4$ on S^1 gives a theory of $N=2, d=4$ supergravity and a truncation (equivalently, a compactification on S^1/\mathbb{Z}_2) gives an $N=1, d=4$ theory.
- Reversing the order of the compactifications, we find that this is equivalent to first reduce $d=11$ supergravity on S^1 to get $N=2, d=10$ and then compactify on CY_3 to $N=2, d=4$ and then truncate (\mathbb{Z}_2) or first truncate $N=2, d=10$ to $N=1, d=10$ supergravity and then to $N=1, d=4$ on CY_3 . In this order you don't see $d=5$.
- Observe that not all $N=2, d=4$ supergravities can be obtained this way: only the cubic models with prepotential $F \sim \frac{C_{IJK} X^I X^J X^K}{X^0}$.
- Another way to arrive to $d=5$ from higher dimensions is via $d=6$. This has not been studied in depth because there is only one $N=(0,1), d=6$ supergravity for a given matter content and the reduction to $N=1, d=5$ just gives a particular model (for that matter content). We have recently discovered that, actually there are 2 6-dimensional matter contents that give rise to exactly the same $N=1, d=5$ model which suggests the existence of an underlying duality between the 2 6-dimensional theories compactified on S^1 . Furthermore, one of the 6-dimensional theories involved arises as the compactification of $N=2, d=10$ on K_3 or (dually) as the compactification of $N=1, d=10$ on T^4 .
- Thus, a generic $N=1, d=5$ supergravity can always be assigned an

11-dimensional origin (if the CY_3 with those Hodge numbers exist) but only a particular model can be given a 6-dimensional origin and, in some respects, 2.

- The 6-dimensional theories can also be obtained from F-theory compactification.

How about the gauged theories? Very complicated. In general, the gaugings have to be already present in higher dimensions. They may arise in the string compactifications (self-dual radii, K_3 singularities...) but this cannot be seen at the level of the supergravity theory.

General classifications of supersymmetric solutions

miércoles, 30 de noviembre de 2016 18:29

Finding supersymmetric solutions is an interesting problem:

- First of all, they are solutions of gravity
- Some of them can play the role of vacua (+ compactification)
- Specially interesting solutions are expected

Unbroken supersymmetry is a very strong condition, as we have stressed, and this opens up the possibility of finding all the supersymmetric solutions or, at least, finding a recipe to construct them all more or less systematically.

For some reason this is usually referred to as "classifying" all the supersymmetric solutions of a theory.

In the $N=1, d=5$ case it would be desirable to do it for all theories simultaneously, studying the most general theory so we can later apply the result to any particular case. This is a very complicated problem, but it can be solved, giving a set of simple equations and conditions whose solutions correspond to solutions of the complete theory.

Working with the most general theory has some drawbacks because we cannot use the simplifications that appear in certain cases, "refining" the classification because some equations become simpler or trivial. Thus, (also for historical and pedagogical reasons) we are going to start by studying the simplest theories first.

There are essentially 2 methods to carry on this task:

- ① Spinorial geometry: gives a very refined classification of the solutions with the different amounts of unbroken supersymmetry they have.
- ② Bilinear method: gives the general form of all the configurations that have some unbroken supersymmetry, irrespective of how much.

We are going to use the second method.

Tod's program

miércoles, 30 de noviembre de 2016 18:46

In 1981 Tod showed how in pure $N=2, d=4$ supergravity one could "classify" all the supersymmetric solutions by using the consistency conditions of the KSEs, (including the integrability conditions).

Nobody tried to repeat this analysis for other supergravity theories until Gauntlett, Gutowski, Hull, Pabis & Reall did it for pure $N=1, d=5$ supergravity. This was due, in fact, to the fact that Tod had used the Newman-Penrose formalism which is not well known among the supergravity / superstring community and is only valid for $d=4$. GGHPR used a different idea: transform the KSEs into equations for the spinor bilinears first and then study the consistency of these equations. This method works in any dimension.

With this modification (and another one we will introduce) the whole program consists in the following steps:

- 1) Assume the bosonic configuration ϕ^b ($\phi^{\bar{5}}=0$) admits at least one Killing spinor ϵ , so the KSEs $\mathcal{D}\epsilon + \phi^b \epsilon = 0$; are satisfied by it. Since these equations are linear we can consider ϵ to be a commuting spinor and operate with it in the standard way.
- 2) Take all the bilinears that can be constructed with ϵ . $\bar{\epsilon}\epsilon, \bar{\epsilon}\gamma^a\epsilon, \dots$ and find which equations they satisfy because ϵ satisfies the KSE: $\mathcal{D}(\bar{\epsilon}\epsilon) = \mathcal{D}\bar{\epsilon}\epsilon + \bar{\epsilon}\mathcal{D}\epsilon = -\bar{\epsilon}\bar{\phi}^b\epsilon - \bar{\epsilon}\phi^b\epsilon$ etc. The resulting equations may not hold all the information contained in the KSEs, but it seems to contain all the information relevant to the problem of finding the ϕ^b .
- 3) Analyse the consistency of the equations of the bilinears. In this analysis we must take into account that not all the bilinears are independent: they satisfy a non-trivial algebra that can be found by using Fierz identities.

4) Once the analysis has been completed finding all the necessary conditions that the supersymmetric configurations must satisfy we have to show that they are also sufficient to ensure the existence of a KS. In all the theories considered so far this has been the case and, at that point one has identified all the supersymmetric configurations of the theory.

5) In order to identify the supersymmetric solutions among the supersymmetric configurations we must impose the equations of motion (2nd order, KSEs: 1st order). The KSIs, expressed in terms of the spinor bilinears, tell us which ones are independent for supersymmetric configurations and need to be imposed.

(The KSIs are equivalent to certain projections of the integrability conditions of the KSEs, but computing the latter can be very hard.)

That's it!

In the $N=1, d=5$ case the spinor bilinears and their algebras are the same for all the theories (only depend on the spinor representation and the Clifford algebra) and we are going to compute them first.

Since the basic supersymmetry transformation rules are also common for all the theories (with the same matter content), the KSIs are also common to all the theories, although the e.o.m. themselves will be different.

Spinor bilinears

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The spinor bilinears that one can construct with just one SM spinor ϵ^i were determined before:

$$\begin{cases} f \equiv i \bar{\epsilon}_i \epsilon^i, & \text{a real function} \\ V^a \equiv i \bar{\epsilon}_i \gamma^a \epsilon^i, & \text{a real vector field} \\ \Phi_{ab}^2 \equiv \bar{\epsilon}_i \gamma_{ab} \sigma_j^2 \epsilon^i, & \text{a triplet of real 2-forms} \end{cases}$$

How are they related? Use the Fierz identities $\hat{i} = 0, 1$

$$\begin{aligned} (\bar{\chi} M \psi) (\bar{\Phi} N \varphi) &= -\frac{1}{8} (\bar{\chi} M \sigma^{\hat{i}} N \varphi) (\bar{\Phi} \sigma^{\hat{i}} \psi) - \frac{1}{8} (\bar{\chi} M \gamma^a \sigma^{\hat{i}} N \varphi) (\bar{\Phi} \gamma_a \sigma^{\hat{i}} \psi) \\ &\quad + \frac{1}{16} (\bar{\chi} M \gamma^{ab} \sigma^{\hat{i}} N \varphi) (\bar{\Phi} \gamma_{ab} \sigma^{\hat{i}} \psi); \\ \downarrow \\ (\bar{\chi}_i \gamma_{ab} M^i \varphi^j) & \end{aligned}$$

$$\Rightarrow \begin{cases} V^a V_a = f^2; \\ V_a V_b = \eta_{ab} f^2 + \frac{1}{3} \Phi_a^i \Phi_{bc}^i; \\ V^a \Phi_{ab}^2 = 0; \\ V^a (*\Phi^2)_{abc} = -f \Phi^i_{bc}; \\ \Phi^2_a{}^c \Phi^3_{cb} = -\delta^{23} (\eta_{ab} f^2 - V_a V_b) - \epsilon^{1st} f \Phi^t_{ab}; \\ \Phi^2_{[ab} \Phi^3_{cd]} = -\frac{1}{4} f \delta^{23} \epsilon_{abcde} V^e; \end{cases}$$

(For higher N this algebra has not been computed)

In view of this algebra there are two different possibilities depending on the causal character of the vector field V^a (non-spacelike $V^2 = f^2 > 0$)

$f \neq 0 \rightarrow V^a$ timelike \rightarrow timelike supersymmetric solutions.

$f = 0 \rightarrow V^a$ null \rightarrow null supersymmetric solutions.

These two cases are studied separately but there are solutions with more than one KS that belong to the two classes. This formalism is not designed to identify them.

KSIs

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The general form is $(\mathcal{E}_b \equiv \frac{\delta S}{\delta \phi^b} \Big|_{\phi^f=0})$

$$\mathcal{E}_b \frac{\delta}{\delta \phi^f} \delta_\epsilon \phi^b \Big|_{\phi^f=0} = 0; \quad \underline{\text{1 relation for each } \phi^f}$$

The boson's supersymmetry rules are, in all $N=1, d=5$ supergravities, given by

$$\delta_\epsilon e^a_\mu = \frac{i}{2} \bar{\epsilon}_i \gamma^a \psi_\mu^i; \quad \rightarrow \mathcal{E}_a{}^\mu$$

$$\delta_\epsilon A^\mu = -i \frac{\sqrt{3}}{2} h^\mu \bar{\epsilon}_i \psi_\mu^i + \frac{i}{2} h^\mu_x \bar{\epsilon}_i \gamma_\mu \lambda^{xi}; \quad \rightarrow \mathcal{E}_I{}^\mu$$

$$\delta_\epsilon \phi^x = \frac{i}{2} \bar{\epsilon}_i \lambda^{xi}; \quad \rightarrow \mathcal{E}_x$$

$$\delta_\epsilon q^x = -i f_{iA}{}^x \bar{\epsilon}_i \Sigma^A; \quad \rightarrow \mathcal{E}_x$$

} different for each theory.

ψ_μ^i :

$$\frac{i}{2} \bar{\epsilon}_i \gamma^a \mathcal{E}_a{}^\mu - i \frac{\sqrt{3}}{2} \bar{\epsilon}_i h^\mu \mathcal{E}_I{}^\mu = 0;$$

λ^{xi} :

$$\frac{i}{2} \bar{\epsilon}_i \gamma_\mu h^\mu_x \mathcal{E}_I{}^\mu + \frac{i}{2} \bar{\epsilon}_i \mathcal{E}_x = 0;$$

Σ^A :

$$-i \bar{\epsilon}_i f_{iA}{}^x \mathcal{E}_x = 0;$$

To convert these identities into tensor identities, we act with ϵ^i , $\gamma^a \epsilon^i$ etc from the right

$$(\bar{\epsilon}^i f_{iA}{}^x \mathcal{E}_x) \epsilon^i = \epsilon^i \bar{\epsilon}^i \epsilon^j f_{iA}{}^x \mathcal{E}_x = -f \delta^i_j f_{iA}{}^x \mathcal{E}_x = -f f_{jA}{}^x \mathcal{E}_x$$

$$f \neq 0 \Rightarrow f_{iA}{}^x \mathcal{E}_x = 0 \Rightarrow \mathcal{E}_x = 0$$

$$f = 0 \Rightarrow \text{nothing}$$

$$(\bar{\epsilon}^i f_{iA}{}^x \mathcal{E}_x) \epsilon^i \gamma^a \epsilon^j = \epsilon^i \bar{\epsilon}^i \gamma^a \epsilon^j f_{iA}{}^x \mathcal{E}_x = -\delta^i_j \gamma^a f_{iA}{}^x \mathcal{E}_x$$

$$f \neq 0 \Rightarrow \text{same conclusion}$$

$$f = 0 \Rightarrow \text{introduce another null vector } W_a; W^2 = 0, W_a V^a = 1$$

$$\Rightarrow \boxed{\mathcal{E}_x = 0} \text{ too}$$

Doing the same in all the KSE's we get

$$\left. \begin{aligned}
 \int E_{\mu\nu} + \frac{\sqrt{3}}{2} h^I E_{I\mu} V_\nu = 0; \\
 E_{\mu\nu} V^\nu + \frac{\sqrt{3}}{2} h^I E_{I\mu} = 0; \\
 E_x V_\mu - \int h_x^I E_{I\mu} = 0; \\
 \int E_x - h_x^I E_{I\mu} V^\mu = 0; \\
 E_x = 0;
 \end{aligned} \right\} \begin{array}{l} \text{in the timelike case} \\ \text{in the timelike case} \end{array}$$

Observe that the derivation of these identities assumes the local existence of the vectors A_μ^I . In practice we often know the field strengths and we have to impose the Bianchi identities $B^I_{\mu\nu} = 0$. In the KSE's only the field strengths occur and these integrability conditions only involve them without assuming $B^I_{\mu\nu} = 0$. Thus, if one derives the above identities from the KSE's integrability conditions one finds that the $B^I_{\mu\nu}$ occur within. They always occur in combination with the Einstein equations in the combination

$$E_{\mu\nu} \rightarrow E_{\mu\nu} + \frac{\sqrt{3}}{2} h_I^* B^I_{\mu\nu}$$

Now, let us see what the above identities look like in the timelike and null cases:

$$\boxed{f \neq 0 \text{ (timelike)}} \quad \text{defining } e^\mu = V_\mu / f$$

$$\left. \begin{aligned}
 E_{ab} + \frac{\sqrt{3}}{2} h^I E_I (a \delta_b) = 0; \\
 h_I^* B^I_{ab} + h^I E_I [a \delta_b] = 0; \\
 E_x - h_x^I E_I = 0; \\
 E_x = 0;
 \end{aligned} \right\}$$

Most of the e.o.m.s are satisfied if $E_I = 0$. E_{ab} requires $E_I = 0$ and the $h_x^I B^I_{ab} = 0$ have to be imposed directly

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\Rightarrow In the timelike case, the only equations that have to be checked explicitly are

$$h^{\nu}_{\ I} \Theta^I_{ab} = 0 ; \quad \mathcal{E}_I^a = 0 ;$$

$$f=0 \text{ (null)}$$

$$V_a \equiv l_a ; \quad W_a \equiv m_a ; \quad m_a l^a = 1 ;$$

$$\begin{aligned} \mathcal{E}_{\mu\nu} l^{\nu} + \frac{\sqrt{3}}{2} h_{\ I}^{\nu} * \Theta^I_{\mu\nu} l^{\nu} &= 0 ; \\ h^I_{\ \nu} \mathcal{E}_I^{\mu} &= 0 ; \\ h_{\nu}^I \mathcal{E}_{I\mu} l^{\mu} &= 0 ; \\ \mathcal{E}_z &= 0 ; \\ \mathcal{E}_x &= 0 ; \end{aligned}$$

Many components to be checked. At least we do not have to check the scalar equations of motion which are typically very involved.

Ungauged pure SUGRA

miércoles, 30 de noviembre de 2016 18:47

Remember this theory only has the supergravity multiplet $\{e_\mu, \psi_\mu, A_\mu\}$ and, therefore only one fermion and only one KSE:

$$\nabla_\mu \epsilon^i - \frac{1}{8\sqrt{3}} F^{\alpha\beta} (\gamma_{\mu\alpha\beta} - 4g_{\mu\alpha}\delta_\beta) \epsilon^i = 0;$$

Deriving equations for the bilinears f, V^μ, Φ^2 are straightforward:

$$\begin{aligned} df - \frac{1}{\sqrt{3}} iV F &= 0; \\ \nabla_\mu V^\mu &= 0; && \leftarrow \text{may} \Rightarrow \text{isom.} \\ dV + \frac{2}{\sqrt{3}} f F + \frac{1}{\sqrt{3}} * (F \wedge V) &= 0; \\ \nabla_\alpha \Phi^{\rho\sigma} + \frac{1}{\sqrt{3}} F^{\beta\gamma} [g_{\alpha\rho} * \Phi^{\beta\gamma} \wedge \delta^\sigma - g_{\alpha\sigma} * \Phi^{\beta\gamma} \wedge \rho \\ &\quad - \frac{1}{2} g_{\alpha[\rho} * \Phi^{\beta\gamma} \wedge \delta^{\sigma]}] = 0; \end{aligned}$$

Some immediate consequences are

$$\begin{aligned} V^\mu \nabla_\mu f &= 0; \Rightarrow \text{invariant under the symmetry generated by } V_\mu \\ d\Phi^2 &= 0; \Rightarrow \text{we'll see.} \end{aligned}$$

To proceed, the timelike and null cases are considered separately

Timelike

Choose an adapted coordinate $V^\mu \partial_\mu = \frac{\partial}{\partial t} \Rightarrow V_\mu dx^\mu = f^2 (dt + \omega)$
 ($\omega \neq 0$ because $V \wedge dV \neq 0$ in general)

$$\Rightarrow ds^2 = f^2 (dt + \omega)^2 - f^{-1} h_{mn} dx^m dx^n;$$

($d=5$ conformally stationary form. $h_{mn} \rightarrow$ "base space metric", Euclidean.

f, ω, h_{mn} time-independent)

$$\nabla^2 \phi = \frac{1}{\sqrt{|g|}} \partial_m \left(\sqrt{|g|} g^{mn} \partial_n \phi \right) = \frac{1}{f^{-1} \sqrt{|h|}} \partial_m \left(\sqrt{|h|} f^{-1} f^{mn} \partial_n \phi \right) = f \nabla_{(4)}^2 \phi$$

\downarrow
time-indep

Using these coordinates, the bilinear identities $\Phi\Phi$ reduce to an identity on the base space:

$$\boxed{\Phi^{\rho}{}_{\alpha n}{}^{\mu} \Phi^{\sigma}{}_{\mu}{}^{\nu} = -\delta^{\rho\sigma} \delta_{nm}{}^{\nu} + \varepsilon^{\rho\sigma\tau} \Phi^{\tau}{}_{m}{}^{\nu}} \quad \boxed{*_{4} \Phi^{\rho} = -\Phi^{\rho}}$$

→ the algebra of hyper-complex structures! Observe that this result only depends on the Clifford algebra and on the choice of coordinates and it will hold true in the timelike case of all $N=1, d=5$ supergravities.

The following property is specific of this case:

$$\boxed{\nabla_{(n} \Phi^{\rho}{}_{m}{}^{\nu} = 0}$$

→ the base space must be a 4-dimensional hyper-Kähler manifold!

The meta field strength contains two pieces: "electric" and "magnetic."

The electric part can be determined from the KSEs and ω

$$-\sqrt{3} d[f(dt+\omega)]$$

and the magnetic is denoted by $-\sqrt{3} \mathcal{H}$ and it is constrained to be self-dual on the base space (\Rightarrow instanton?)

$$\Rightarrow \boxed{F = -\sqrt{3} \{ d[f(dt+\omega)] + \mathcal{H} \} ; *_{4} \mathcal{H} = +\mathcal{H} ;}$$

The last condition involves ω

$$\boxed{(d\omega)^{\dagger} = -\frac{3}{2} f^{-1} \mathcal{H} ;}$$

These are the necessary conditions for unbroken timelike supersymmetry.

Plugging them into the KSEs we see that

$$\boxed{\varepsilon^i = f^{1/2} \varepsilon_0^i ; \quad \frac{1}{2} (1-\gamma^0) \varepsilon_0^i = 0 ;}$$

solves them. Thus, although we only assumed the existence of one Killing spinor, we see that there are at least 4 in every timelike supersymmetric configuration:

$$\left\{ \frac{1}{2} (1-\gamma^0) \right\}^2 = \frac{1}{4} (1+(\gamma^0)^2 - 2\gamma^0) = \frac{1}{4} 2(1-\gamma^0) \Rightarrow \text{projector.}$$

$$T_2 \gamma^0 = 0 ; (\gamma^0)^2 = +1 \Rightarrow \dim \mathcal{K}_a(1-\gamma^0) = 2 (\times 2 \text{ complex}) = 4 .$$

Now we want to determine which of these supersymmetric configurations are solutions. Imposing the Maxwell and Bianchi identities we arrive at these two equations

$$\boxed{\begin{aligned} \nabla_{(4)}^2 f^{-1} - \frac{1}{4} \textcircled{4} \cdot \textcircled{4} &= 0; \\ d\textcircled{4} &= 0; \end{aligned}} \quad (\Rightarrow \text{Klein instanton!})$$

Problem solved! Only interesting features and side structure.

Solving these equations will require making ansatz, though. The general solution is not known.

Ansatz $l_\mu \equiv V_\mu$; $l^\mu \partial_\mu \equiv \partial_{\underline{v}}$; $l_\mu dx^\mu = \int (du + \omega)$
 $f \neq 0$ in this case because $dl = -\frac{1}{\sqrt{3}} * (F \wedge l) \neq 0$
 $\omega = 0$ in this case because $l \wedge l = 0$ ($l^2 = 0$)

$$\boxed{ds^2 = 2f du (dv + H du + \omega) - f^{-2} \gamma_{rs} dx^r dx^s;}$$

$f, H, \omega, \gamma_{rs}$ v -independent. (May depend on u and x^i)

In this case, the bilinear identities $\nabla \Phi$ lead to the conditions

$$\Phi^2 = du \wedge v^2; \quad v^2_\pm v^i_\pm = \gamma_{\pm i}$$
 (Dreibein)

and the equation $d\Phi^2 = 0$ leads to $d v^2 = 0 \Rightarrow v^2 = dx^2$

$$\gamma_{rs} = \delta_{rs}$$

Finally

$$\boxed{F = \left[\frac{1}{\sqrt{3}} f^2 *_{(3)} (d_{(3)} \omega) \right] \wedge du + \sqrt{3} *_{(3)} d_{(3)} f^{-1};}$$

f, H, ω, dx^2 unconstrained beyond the fact that they are v -indep.

These are the necessary conditions.

They are also sufficient: the KSTSS are solved for all these backgrounds for any u -independent ε^i satisfying $\gamma^+ \varepsilon^i = 0 \Rightarrow \frac{1}{2}$ BPS.

Now, let us consider the equations of motion.

The analysis of the equations of motion shows that they are solved for

$$\nabla_{(3)}^2 K = 0; \quad \nabla_{(3)}^2 L = 0, \quad \nabla_{(3)}^2 N = 0;$$

$$f^{-1} = K; \quad M = L/K; \quad H = -\frac{1}{2} LM + N$$

$$*_{(3)} \hat{\Delta} \omega = \sqrt{3} (L \wedge K - K \wedge L) - 3 K^2 \omega; \quad \Delta \omega \equiv *_{(3)} dK$$

$$K \partial_x K = 0;$$

Ungauged SUGRA coupled to vectors and/or hypers

miércoles, 30 de noviembre de 2016 18:48

Let us consider now the coupling to vector multiplets and hypermultiplets.

The KSEs are now

$$D_\mu \varepsilon^i - \frac{1}{8\sqrt{3}} h_I F^{I\alpha\beta} (\gamma_{\mu\alpha\beta} - 4g_{\mu\alpha}\gamma_\beta) \varepsilon^i = 0;$$

$$(\not{D}\not{\phi}^x - \frac{1}{2} h^x_I F^I) \varepsilon^i = 0;$$

$$f_x^{iA} \not{p} q^x \varepsilon_i = 0;$$

The equations derived for the spinor bilinears in the pure ungauged hyper case have the same form with the replacement $\nabla_\mu \rightarrow D_\mu$ (SO(2)-covariant) and $F \rightarrow h_I F^I$ (new graviphoton).

$$\begin{aligned} df - \frac{1}{\sqrt{3}} i_V h_I F^I &= 0; \\ \nabla_{(\mu} V_{\nu)} &= 0; \quad \leftarrow \text{may} \Rightarrow \text{isom.} \\ dV + \frac{2}{\sqrt{3}} \int h_I F^I + \frac{1}{\sqrt{3}} * (h_I F^I \wedge V) &= 0; \\ D_\alpha \Phi^{\rho\gamma} + \frac{1}{\sqrt{3}} h_I F^{I\sigma\tau} \left[g_{\sigma\rho} * \Phi^2 \gamma_{\tau\alpha} - g_{\sigma\alpha} * \Phi^2 \gamma_{\rho\tau} - \frac{1}{2} g_{\alpha[\rho} * \Phi^2 \gamma_{\tau]\sigma} \right] &= 0; \end{aligned}$$

$$\Rightarrow V^\mu \partial_\mu f = 0; \quad D\Phi^2 = 0;$$

But now there are algebraic equations that follow from the 2 new KSEs:

$$\begin{aligned} h^x_I F^I{}_{\alpha\beta} \Phi^{2\alpha\beta} &= 0; \\ \int d\phi^x + h^x_I i_V F^I &= 0; \\ \Phi^{\rho\gamma} \partial^\nu \phi^x + \frac{1}{4} \varepsilon_{\mu\nu\alpha\beta} h^x_I F^{I\nu\alpha} \Phi^{2\beta\gamma} &= 0; \\ \not{L}_V \not{q}^x &= 0; \\ \int \not{D}_\mu q^x + \Phi^{\rho\gamma} \not{D}_\mu q^\gamma g^{\rho x} &= 0; \end{aligned}$$

$$V^\mu \partial_\mu \phi^x = 0; \quad V^\mu \partial_\mu q^x = 0;$$

Let's consider separately the timelike and null axes:

Similike → Same coordinate bases

The metric can be written in the same abstract form. The Φ^i_{mn} are anti-self-dual forms defined on the base space and satisfy the same algebra. The difference is that, now, instead of $\nabla_{[m} \Phi^i_{np]} = 0$ we find

$$\boxed{\nabla_{[m} \Phi^i_{np]} = 0}$$

This looks like a QK manifold. However 4d QK manifolds are defined in a different way because having $SO(2) \times SO(2) \sim SO(4)$ is not a restriction at all. Often QK manifolds are required to have $\dim \geq 8$.

The above equation must be understood as a relation between the anti-self-dual part of the Levi-Civita connection and the pullback of the $SO(2)$ connection of the QK space of the hypers. In the frame in which the Φ^i_{mn} are constant

$$\boxed{\omega_{(4)mn}{}^k = -\Lambda^2 \times \partial_m g^X \Phi^i{}^2{}_n{}^k}$$

When Λ^2 is trivial ($M_4=0$) $\omega_{(4)}$ is self-dual and the base space is HK.

The equation that involves the hyperscalars can be put in the form

(Generalisation of the Caudrey-Pearson equations) $\left\{ \begin{aligned} \partial_m g^X &= \Phi^i{}^2{}_m{}^n \partial_n g^Y \Phi^j{}^2{}_Y{}^Z \\ \partial_m \partial^n g^X &= 0 \quad (E_X = 0) \end{aligned} \right.$ = "quaternionic metric"

Not many solutions of these equations are known...

Finally, the vector field strengths take the form

$$\boxed{\vec{F}^I = -\sqrt{3} \left\{ d[fh^I(dt+\omega)] + \mathbb{Q}^I \right\}; \quad \star \mathbb{Q}^I = + \mathbb{Q}^I}$$

and

$$\boxed{(d\omega)^+ = -\frac{3}{2} \frac{h^I}{f} \mathbb{Q}^I}$$

(The anti-selfdual part follows by demanding $\star^2 \omega = 0$.)

These are the necessary conditions for supersymmetry. Observe that the

The only constraint of the h^I is that they have to be form-independent.
These conditions ensure the existence of Killing spinors satisfying

$$\varepsilon^i = f^{1/2} \varepsilon^i_0; \quad \frac{1}{2}(1-\gamma_0)\varepsilon^i = 0;$$

$$\frac{1}{2} \left[\delta + \frac{1}{4} \gamma^{\alpha\beta} \sigma^{\alpha\beta} \right] \varepsilon^i = 0;$$

The last 3 conditions ($\alpha=1,2,3$) are needed only if the corresponding components $\Delta^i \neq 0$. They are projectors only on the subspace that satisfies the first condition. They satisfy the $SU(2)$ algebra so imposing 2 is equivalent to imposing the 3rd.

The meaning of the last projectors is that $\gamma^{\alpha\beta}$ and $\sigma^{\alpha\beta}$ have the same effect on the Killing spinors and the $SU(2)$ of the tangent space is identified with the $SU(2)$ of R -symmetry.

Each of these conditions reduces the number of independent KS by a half:

$$\text{no hypers} \Rightarrow \textcircled{1/2} \text{ BPS}$$

$$1 \text{ extra condition} \Rightarrow 1/2 \times 1/2 = \textcircled{1/4} \text{ BPS}$$

$$2 \text{ extra conditions} = 3 \text{ extra conditions} \Rightarrow 1/2 \times 1/2 \times 1/2 = \textcircled{1/8} \text{ (the minimum)}$$

Finally the supersymmetric solutions must satisfy these equations:

$$\nabla_{(M}^2 \left(\frac{h^I}{f} \right) - \frac{1}{4} C_{IJK} \omega^J \cdot \omega^K = 0;$$

$$d \omega^I = 0;$$

Again, Abelian self-dual instantons on a HK ($u_H=0$) or QK ($u_H \neq 0$ + nontrivial g_X) manifold.

Chull

We make the same coordinates and we get a metric of the same form

Now, however $\mathbb{F}^I = du \wedge v^I \oplus \mathcal{D}\mathbb{F}^I = 0 \Rightarrow du \wedge \mathcal{D}v^I = 0$
 $\Rightarrow \mathcal{D}_{(3)} v^I = 0$ which can be interpreted as Cartan Structure equations for the Dreibein v^I and the 3-d Levi-Civita connection

$$\omega_{(3)2}^{st} = 2 \varepsilon^{stk} \omega_{[k} \partial_{s]} g^X$$

(Again, a relation between the Levi-Civita connection of the base space (here transverse space or world-volume space) and the $SO(2)$ connection of the KK space, but now it determines the LC connection completely)

The hypercalors must satisfy now

$$\partial_{[2} g^X \omega_{X}^{iA} \sigma_{i]j} = 0;$$

The vector field lengths have the form

$$\begin{aligned} F^I &= \left[\frac{1}{\sqrt{3}} f^2 h^I \ast_{(3)} d_{(3)} \omega - \psi^I \right] \wedge du + \sqrt{3} \ast_{(3)} d_{(3)} \left(\frac{h^I}{f} \right) \\ h_I \psi^I &= 0; \end{aligned}$$

These conditions are necessary for supersymmetry and they are also sufficient to ensure the existence of KS satisfying

$$\mathcal{D}_\nu \varepsilon^i = 0; \quad \gamma^+ \varepsilon^i = 0; \quad (\text{operal gauge!})$$

$$\frac{1}{2} \left\{ 1 - \gamma^{(1)} \sigma^{(2)} \right\} \varepsilon = 0$$

The additional conditions are similar to those of the binelike and the amount of unbroken supersymmetry is the same.

The analysis of the equations of motion is complicated but in the end the solutions are given in terms of functions K^I, L_I, N harmonic in the 3-d base space plus a number of horrible gauge-fixing conditions.

$$K^I = h^I / f; \quad L_I = G_{JK} K^J M^K; \quad H = \frac{1}{2} G_{JK} K^J M^K + N \text{ etc.}$$

Pure, gauged supergravity

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(A.k.a. minimal gauged $d=5$ supergravity)

At the bosonic level, this theory differs from the ungauged one in the cosmological-constant term $V = -4g^2 = +3\Lambda$; $\Lambda = -\frac{4}{3}g^2 < 0$

At the fermionic level the theory has more important differences: all the spinors (here it is just the gravitinos) are charged w.r.t. the graviphoton so their covariant derivatives must contain a U(1) connection and the supersymmetry transformation rules acquire a fermion shift term:

$$\delta_\epsilon \psi_\mu^i = \mathcal{D}_\mu \epsilon^i - \frac{1}{8\sqrt{3}} F^{\alpha\beta} (\gamma_{\mu\alpha\rho} - 4g_{\mu\alpha}\delta_\rho) \epsilon^i + \frac{i}{2\sqrt{3}} g P^2 (\sigma^2)_j{}^i \gamma_\mu \epsilon^j;$$

with
$$\mathcal{D}_\mu \epsilon^i = \nabla_\mu \epsilon^i + ig A_\mu P^2 (\sigma^2)_j{}^i \epsilon^j;$$

Any non-vanishing value of P^2 is possible (usually we normalize $P^1 P^2 = 1$) but it is sometimes helpful to pick $P^2 = \delta^2_1$, for instance.

There are many things that do not change (KSTs), but we expect additional terms in the equations of the bilinears plus the replacement $\nabla_\mu \rightarrow \mathcal{D}_\mu$. We know this derivative plays an important rôle in the identification of the base space.

The final result can be presented as follows: the timelike supersymmetric solutions are determined by \hat{f} , $\hat{\omega}_{\underline{m}} dx^{\underline{m}}$, $\hat{h}_{\underline{m}\underline{n}} dx^{\underline{m}} dx^{\underline{n}}$, the hypercomplex structure $\hat{\Phi}^{\hat{r}}_{\underline{m}\underline{n}}$ and the vector field $\hat{A}_{\underline{m}}$.

- $\hat{\Phi}^{\hat{r}}$ is covariantly-constant w.r.t. the U(1)-covariant derivative on the base space:
$$\hat{\mathcal{D}}_{\underline{m}} \hat{\Phi}^{\hat{r}}_{\underline{m}\underline{k}} = \hat{\nabla}_{\underline{m}} \hat{\Phi}^{\hat{r}}_{\underline{m}\underline{k}} + g \epsilon^{\alpha\beta} P^\alpha \hat{A}_{\underline{m}} \hat{\Phi}^{\hat{r}}_{\underline{m}\underline{k}} = 0$$

- $(d\hat{\omega})^+ = -\frac{3}{2} \hat{f}^{-1} \hat{\Theta}$; $\hat{\Theta} = -\frac{1}{\sqrt{3}} (d\hat{A})^+ = -\frac{1}{\sqrt{3}} \hat{F}^+$

- $\hat{F}^- = (d\hat{A})^- = -2 \hat{f}^{-1} P^2 \hat{\Phi}^{\hat{r}}$ (= 0 in the ungauged case)

$\hat{F} = \hat{F}^+ + \hat{F}^- = -\sqrt{3} \hat{\Theta} - 2 \hat{f}^{-1} P^2 \hat{\Phi}^{\hat{r}}$

- $\hat{\nabla}^2 \hat{f}^{-1} - \frac{1}{6} \hat{F} \cdot \hat{F} - \frac{1}{2\sqrt{3}} \hat{F} \cdot f(d\hat{\omega})^- = 0$

Solving these equations we find the building blocks. The physical

fields are given by

$$\begin{cases} ds^2 = \hat{f}^2 (\lambda t + \hat{\omega})^2 - \hat{f}^{-1} h_{mn} dx^m dx^n \\ A = -\sqrt{3} \hat{f} (\lambda t + \hat{\omega}) + \hat{A}; & (A_m = \hat{A}_m - \sqrt{3} \hat{f} \omega_m); \\ \hookrightarrow \hat{F} = -\sqrt{3} d[\hat{f} (\lambda t + \hat{\omega})] + \hat{F}; \end{cases}$$

One can go much further: the equation $\hat{\mathcal{D}}_m \hat{\Phi}^2_{mk} = 0$ implies that the $SU(2)$ singlet \hat{F}^2_{mn} is a covariantly constant complex structure on the base space, which is a Kähler space.

Choosing $\hat{F}^2 = \hat{\sigma}^2_3$

$$\hat{\mathcal{D}}_m \hat{\Phi}^2_{mk} = 0 \Rightarrow \begin{cases} \hat{\nabla}_m \hat{\Phi}^1_{mk} = 0 & \hat{\Phi}^1_{mn} \equiv K_{mn} \\ \hat{\nabla}_m \hat{\Phi}^2_{mk} = g \hat{A}_m \hat{\Phi}^3_{mk}; \\ \hat{\nabla}_m \hat{\Phi}^3_{mk} = -g \hat{A}_m \hat{\Phi}^2_{mk}; \end{cases} \rightarrow \text{integrability}$$

$$\rightarrow \boxed{\begin{array}{l} \hat{R}_{mn} = g \hat{F}_{mn}; \\ \hat{F}^{-1}_{mn} = -2g \hat{f}^{-1} K_{mn}; \end{array}} \rightarrow \hat{R} = 8g^2 \hat{f}^{-1}$$

The null case will not be covered due to lack of time.

N=1, d=5 SEYM theories

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These are the simplest supersymmetrisation of the d=5 Einstein-Yang-Mills (EYM) theories. Supersymmetry requires the vectors to come in full vector supermultiplets, and, thus, these theories have one real scalar for each vector (minus one). No hypos are needed. On the other hand, the gauge group must be non-Abelian for the gauging to be non-trivial. In these theories, the scalar potential vanishes identically because the fermion shifts also vanish identically.

The spinor fields are unchanged and their covariant derivatives only have the Levi-Civita connection. The only changes in the KSEs are, therefore, the replacement of $\partial \phi^x$ by $\mathcal{D} \phi^x$ and $F^I = dA^I$ by the gauge-covariant \hat{F}^I . The same will be true in the equations of the KS fermions. The results will be the gauge-covariant version of those obtained for ungauged supergravity coupled to vector multiplets only:

The timelike supersymmetric solutions are constructed from the building blocks $\hat{\Delta}_m^{\pm} dx^m$, \hat{f}_I , $\hat{\omega}$ defined on h_{min} satisfying the conditions and equations

$$\left\{ \begin{array}{l} - h_{\text{min}} dx^m dx^m \text{ is hyper Kähler.} \\ - * \hat{F}^{\pm}(\hat{\Delta}) = + \hat{F}^{\pm} \Rightarrow \text{non-Abelian self-dual instantons on HK spaces!} \\ - \hat{\mathcal{D}}^2 \hat{f}_I - \frac{1}{6} C_{IJK} \hat{F}^J \cdot \hat{F}^K = 0 \\ - (d\hat{\omega})^{\pm} = \sqrt{3} \hat{f}_I \hat{F}^{I\pm}; \end{array} \right.$$

Then, using these building blocks, the physical fields are obtained:

- Define \hat{f} by $h_I / \hat{f} \equiv \hat{f}_I$; The h_I satisfy a constraint which is homogeneous of order $3/2$ in the h_I $F(h.) = 1$
 $\Rightarrow F(f.) = \hat{f}^{-3/2} \Rightarrow h_I = \hat{f}_I \hat{f}^{-2/3}(f.) \Rightarrow h^I$
- A definition of the scalars that always works is $\phi^x = \frac{h_x}{h_0} = \frac{\hat{f}_x}{\hat{f}}$
- $ds^2 = \hat{f}^2 (dt + \hat{\omega})^2 - \hat{f}^{-1} h_{\text{min}} dx^m dx^m$

$$\begin{aligned} - \Delta^I &= -\sqrt{3} h^I \hat{f}(\lambda t + \hat{\omega}) + \hat{A}^I; \\ \alpha F^I &= -\sqrt{3} \hat{\partial} [h^I \hat{f}(\lambda t + \hat{\omega})] + \hat{F}^I; \end{aligned}$$

Again we will focus on the funnellike case and leave the null case aside.

The additional isometry trick

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One of the main problems we face in order to find general families of solutions is that we need to be able to give the general form of the base space. Otherwise we are restricted to solving the equations for a particular base space and then for another etc.

However, the general form of a Kähler or hyperKähler metric is not known.

In the hyperKähler case, though, we know the general form of the metrics that admit a biholomorphic isometry: Gibbons-Hawking metrics:

$$h_{\mu\nu} dx^\mu dx^\nu = H^{-1} (dz + \gamma)^2 + H d\vec{x}^2$$

with $d\gamma = *_{\mathbb{R}^3} dH$ ($\Rightarrow d*_{\mathbb{R}^3} dH = 0$; harmonic in \mathbb{R}^3)

Using this general form we can try to solve the necessary and sufficient conditions satisfied by the truncate supersymmetric solutions of the $N=1, d=5$ supergravity with no hyper and no FI terms.

In the Kähler case several ansätze for Kähler metrics with more than one isometry (toric, axi-symmetric) have been proposed. More recently we have proposed one for Kähler metrics with one isometry that is connected to the Gibbons-Hawking ansatz:

$$h_{\mu\nu} dx^\mu dx^\nu = H^{-1} (dz + \gamma)^2 + H [d\varrho^2 + W^2 (dx^2 + dy^2)]$$

$$\left. \begin{aligned} 2\partial_x [\gamma_S] &= \partial_y H; \\ 2\partial_y [\gamma_S] &= -\partial_x H; \\ 2\partial_y [\gamma_x] &= \partial_S (W^2 H); \end{aligned} \right\} \partial_x \partial_x H + \partial_y \partial_y H + \partial_S \partial_S (W^2 H) = 0$$

$W=1 \Rightarrow$ hyperKähler, but there are intermediate possibilities.

These ansätze also offer naturally the possibility of dimensional reduction of the solution to $d=4$, connecting with those of $N=2, d=4$.

Gibbons-Hawking ansatz

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Let's consider this ansatz in the context of $N=1, d=5$ SEYM theories. These theories always admit a $g \rightarrow$ limit in which the ansatz is also valid.

The building blocks of any bimetric asymptotically flat solution are

- 1.- A hyperkähler metric \rightarrow Gibbons-Hawking
- 2.- A self dual \hat{F}^I on the HK space \rightarrow we use the following result by Kraheimmer relating YM instantons on HK with YM monopoles on \mathbb{E}^3

$$\oint \hat{*} \hat{F}^I(\hat{A}) = + \hat{F}^I(\hat{A}) \quad \text{and} \quad \begin{cases} \hat{A}^I_{\underline{z}} \equiv \frac{1}{2\sqrt{6}} (-\hat{A}_{\underline{z}} + \varphi_{\underline{z}} \hat{A}_{\underline{z}}); & \underline{z} = 1, 2, 3 \\ \hat{\Phi}^I \equiv \frac{1}{2\sqrt{6}} H \hat{A}^I_{\underline{z}}; \end{cases}$$

then $\boxed{\hat{F}^I(\hat{A}) = *_{\mathbb{E}^3} \hat{\Phi}^I}$ in \mathbb{E}^3 Yang-Mills equations $\hat{\Phi}^I \rightarrow \text{Higgs}$

- 3.- The solutions f_I to the equation

$$\hat{\partial}^2 f_I - \frac{1}{6} G_{IJK} \hat{F}^J \cdot \hat{F}^K = 0$$

on the HK space \rightarrow Knowing the GH metric and the instanton/monopole fields (\rightarrow Higgs fields) we are going to reduce this equation to a much simpler one

- 4.- The solution $\omega_{\underline{m}} dx^{\underline{m}}$ to the equation \rightarrow now it will be easier to find

$$(d\hat{\omega})^+ = \sqrt{3} \hat{f}_I \hat{F}^I$$

In order to solve the equations for the building blocks it is convenient to introduce new variables:

$$L_I \equiv \hat{f}_I - 8 G_{IJK} \hat{\Phi}^J \hat{\Phi}^K / H;$$

$$\hat{\omega} \equiv \omega_5 (dx^4 + \varphi) + \omega_{\underline{z}} dx^{\underline{z}};$$

$$M \equiv \omega_5 - 16\sqrt{6} G_{IJK} \hat{\Phi}^I \hat{\Phi}^J \hat{\Phi}^K / H^2 + 3\sqrt{2} L_I \hat{\Phi}^I / H;$$

$$\hat{A}^I \equiv 2\sqrt{6} [H^{-1} \hat{\Phi}^I (dx^4 + \varphi) - \hat{A}^I]; \quad (\text{Kraheimmer})$$

Then, the whole problem is reduced to the following equations for the new variables $\underbrace{H, M, \hat{\Phi}^I, L_I}_{\text{functions}}, \underbrace{\omega, \hat{A}^I, \varphi}_{\text{1-forms}}$ in \mathbb{E}^3

$$\left\{ \begin{array}{l} d\star_3 dM = 0; \\ \star_3 dH = dY; \\ \star_3 \ddot{\Phi}^I = \frac{U}{T}^I; \end{array} \right\} \rightarrow \text{Bogomol'nyi monopole-like eqs.}$$

$$\ddot{\Phi}^2 L_I = g^2 f_{IJ}^L f_{KL}^M \Phi^J \Phi^L L_M;$$

$$\star_3 d\omega = H dM - M dH + 3 \partial (\Phi^I \ddot{\Phi} L_I - L_I \ddot{\Phi}^I);$$

"↑
Bubbling equations"

We will see specific solutions of these equations. For the moment, abstract that M and H are harmonic functions in \mathbb{R}^3 and many are known. On the other hand, all the spherically-symmetric solutions of the Bogomol'nyi equation ^{for $SO(2)$} were found by Prasad long time ago. Particular examples are the 't Hooft-Polyakov monopole in the BPS limit and the $SO(2)$ Wu-Yang monopole. However, these are not the most interesting solutions because they lead to singular instantons. The most interesting ones are the "clashed monopoles" that correspond to the BPST $SO(2)$ instanton and for which Ramirez has found multi-charge solutions (also dyonic, involving $L \neq 0$). The "bubbling equations" always admit a solution if the other equations are solved: the integrability equations seem to be satisfied. However, the harmonic functions in \mathbb{R}^3 have singularities and making sure the integrability conditions are satisfied there leads to important constraints in the locations of the singularities (BPs) discovered by Denef and Bates. The "Higgs" fields that appear in the Abelian Bogomol'nyi equations are always harmonic functions. This will not be the case in the non-Abelian case using Ramirez's dyonic solution.

What happens if the integrability conditions are not satisfied at the singularities? \rightarrow ω has to be defined patch by patch and gluing them usually requires time to be periodic \rightarrow CTCs.

Iso-Kähler ansatz

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The ansatz made for the Kähler metric of the base space allows one to solve immediately the equations that involve the metric functions f and the components \hat{A}_m of the single vector field of minimal gauge $N=1, d=5$ supersymmetry:

$$\begin{cases} g \hat{A}_m = \hat{I}_m^{\quad n} \partial_n \log W; \\ g^2 \hat{f}^{-1} = \hat{V}^2 \log W^2; \end{cases} \quad (\text{Remember } A = -\sqrt{3} \int (dt + \hat{\omega}) + \hat{A})$$

However, in this theory, these fields are also constrained by other equations. Plugging these solutions in them will lead to differential equations of up to fourth order (other ansatz give 6th order differential equations) involving W^2 .

(It is important to notice that in the SEYM case one chooses first the 6th space (H) and then solves the equations in that space. Here it is different: different solutions have different K base spaces (W, H) and one needs to determine them through simple ansatz).

It is convenient to make a change of variables similar to that of the SEYM case:

$$\begin{aligned} L &= \int^{-1} - \frac{1}{12} K^2/H; & (K \text{ similar to } \mathbb{F} \text{ but, here } gK = \partial_3 \log W^2) \\ \hat{\omega} &= \omega_2 (dt + \gamma) + \omega; & \Rightarrow L \text{ is completely determined by } H, W \\ M &= \omega_2 - \frac{\sqrt{3}}{4} LK/H - \frac{1}{2\sqrt{3}} \sqrt{3}/H; \end{aligned}$$

In terms of these variables, the equations that need to be solved are

$$\ast_3 d\omega = H \wedge M - M \wedge H + \frac{\sqrt{3}}{4} (K \wedge L - L \wedge K) - H \left(\omega_2 \partial_3 \log W^2 - 2\sqrt{3} g \hat{f}^{-2} \right) ds;$$

$$\bar{\nabla}^2 L = 4H (gL)^2 - \frac{2}{3} H (gK)^2 - \frac{4}{3} gL \partial_3 K - \frac{1}{3} gK \partial_3 L + \frac{4}{3} H g \partial_3 M; \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \text{ useful}$$

$$\bar{\nabla}^2 M = -\sqrt{3} L (gKL + 2\partial_3 L);$$

These equations ensure the integrability of that of ω .

In solving these equations we must take into account that \hat{f} , K , H and L are completely determined by W through

$$\begin{cases} \partial_x^2 H + \partial_y^2 H + \partial_s^2 (W^2 H) = 0; \\ g K = \partial_s \log W^2; \\ L = \frac{1}{8g^2 H} \left\{ \bar{\nabla}^2 \log W^2 - \frac{2}{g} (\partial_s \log W^2)^2 \right\}; \\ \hat{f}^{-1} = \frac{1}{8g^2} \hat{\nabla}^2 \log W^2; \end{cases}$$

\Rightarrow 4th-order equations for W^2 .

Some of the most remarkable supersymmetric solutions

miércoles, 30 de noviembre de 2016 18:34

The theories of $N=1, d=5$ supergravity are characterized by the richness of their supersymmetric solutions. In this section we are going to review some of the most interesting. This will also illustrate how one constructs complete, physically meaningful solutions from the building blocks supersymmetry indicates we must use.

Maximally supersymmetric solutions

miércoles, 30 de noviembre de 2016 18:52

As we mentioned in our general introduction to supersymmetric solutions, these are interesting because they can be seen as vacua of the theory.

To find these solutions one must use a combination of techniques, since the one we have described does not take into account the number of KS and only ensures there is one. One must study the integrability conditions of the KSEs and study the KSEs by themselves.

First of all, to find the maximally supersymmetric solutions it is enough to consider free (or free gauged) supersymmetry: the additional KSEs are always algebraic constraints on the KS that cannot be solved for non-trivial matter fields (terms of different order in δ -metrics etc.).

Let us summarize the results. The maximally supersymmetric solutions of

ungauged

Chinkoroban

Gauged (F1)

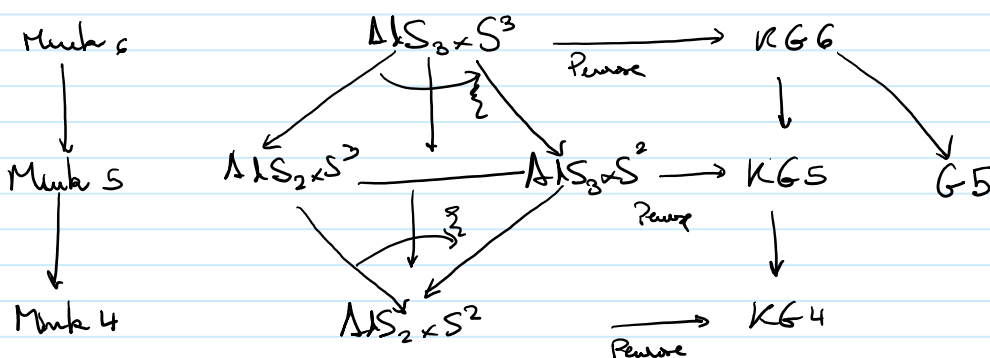
ΔS_5

KS

$$\Delta S_2 \times S^3 \xrightleftharpoons[\text{integrability conditions}]{\text{1-parameter}} \Delta S_3 \times S^2$$

Gödel

For the ungauged case, most of them are related to the maximally supersymmetric vacua of the 6- and 4-dimensional theories with 8 supersymmetries: $N=(0,1), d=6$ and $N=2, d=4$:



The solutions of the 1-parameter family that interpolates between $AdS_2 \times S^3$ (the near-horizon limit of extremal BPS) and $AdS_3 \times S^2$ (the near-horizon limit of extremal BS) arise as the near-horizon limits of the BTZ rotating BH and the parameter ξ is related to the angular momentum. We will derive them in this way.

The KGS is a homogeneous pp-wave (Hpp) that can be obtained as the Penrose limit of $AdS_3 \times S^2$.

The maximally supersymmetric vacuum that is not connected to the rest in an obvious way is GS, which is a homogeneous solution similar to the Gödel solution of $d=4$ (but with some differences because here we do not have cosmological constant). It is given by

$$ds^2 = (dt + \omega)^2 - d\vec{x}_{(4)}^2, \quad A = -\sqrt{3} \omega, \quad \omega = \frac{1}{\sqrt{3}} \lambda (\underbrace{x^1 dx^2 - x^2 dx^1}_{\text{Killing forms of } \mathbb{R}^2})$$

($\hat{f} = 1$, $h_{\mu\nu} \rightarrow \mathbb{R}^4$)

In the gauged theory there are duals (but not maximally supersymmetric) solutions.

Asymptotically-flat BHs with Abelian charges

miércoles, 30 de noviembre de 2016 18:52

... of $N=1, d=5$ supergravity coupled to vector supermultiplets (Observe: the presence of hyper can be seen as hair and does not allow the construction of regular black holes, at least in the ungauged theory).

As a rule supersymmetric BHs belong to the family class.

Which HK base space to choose? We can use the Gt ansatz because it includes \mathbb{R}^4 ($H=1, \alpha=0$) and also $\mathbb{R}^4_{-b^2}$ ($H=\frac{1}{|x^2|}, \alpha=\cos \theta$) which we know to occur in simple solutions.

In the Abelian case the equations of the building blocks are

$$\begin{cases} d *_3 dM = 0; \\ *_3 dH = d\alpha; \rightarrow d *_3 dH = 0 \\ *_3 d\bar{\Phi}^I = d\bar{A}^I; \rightarrow d *_3 d\bar{\Phi}^I = 0 \\ d *_3 dL_I = 0; \\ *_3 d\omega = H dM - M dH + 3 \Omega^I (\bar{\Phi}^I dL_I - L_I d\bar{\Phi}^I). \end{cases}$$

and, therefore, a solution is completely determined by the choice of harmonic functions on \mathbb{H}^3 $H, M, \bar{\Phi}^I, L_I$ such that the integrability conditions of the equation for ω are satisfied everywhere on \mathbb{R}^3 .

If we want to describe a single BH on a spherically symmetric choice is most appropriate: $H=1$ (\mathbb{R}^4) and $H=\frac{1}{r}$ ($\mathbb{R}^4_{-b^2}$)

The first choice is really not good since we have reduced the problem to \mathbb{H}^3 because we will get harmonic functions on \mathbb{H}^3 with $SO(3)$ but not $SO(4)$ symmetry. We could have done this before, but, in that case it was difficult to solve all the equations explicitly, except if we set $\bar{A}^I = 0 \Rightarrow$

$$\begin{cases} \hat{\nabla}^2 f_I = 0 & f_I \sim a_I + \frac{q_I}{r}; \quad r = |\vec{x}_{(4)}| \\ \hat{\omega} = 0 & \rightarrow ds^2 = \hat{f}^2 dt^2 - \hat{f}^{-1} (dr^2 + r^2 d\Omega^2(r)); \\ F^I = d\{f^I\} \wedge dt \end{cases}$$

These are purely electric, static BHs. This may seem to be enough but

there is a subtle issue in these theories (violating no-hair/uniqueness thes)

If we choose $H = \frac{1}{r}$, the HK space \Rightarrow

$$h_{\text{min}} dx^\mu dx^\nu = r (dr + \cos \theta d\varphi)^2 + \frac{1}{r} (dx^2 + r^2 d\Omega^2_{(2)})$$

$$r = \frac{\rho^2}{4} \rightarrow = \frac{\rho^2}{4} (dr + \cos \theta d\varphi)^2 + \frac{4}{\rho^2} \left(\frac{\rho d\rho}{2}\right)^2 + \frac{\rho^2}{4} d\Omega^2_{(2)}$$

$$\begin{aligned} dr &= \frac{1}{2} \rho d\rho \\ &= d\rho^2 + \rho^2 \frac{1}{4} \left[(dr + \cos \theta d\varphi)^2 + d\Omega^2_{(2)} \right] \\ &= d\rho^2 + \rho^2 d\Omega^2_{(3)} \rightarrow \mathbb{F}^4_{-10} \end{aligned}$$

and the harmonic functions in \mathbb{F}^3 $a + \frac{b}{r}$ become $a + \frac{4b}{\rho^2}$ harmonic functions in \mathbb{F}^4_{-10} , so the solutions will have (in principle) $SO(4)$ symmetry.

Observe that, for harmonic functions of this kind $\star d\omega = 0$ everywhere and, thus, $\omega = 0$. There is still ω_5 , of course.

Summarizing: the solutions are determined by

$$H = 1/r; \quad \Phi^I = c^I + \frac{f^I}{r};$$

$$M = a + b/r; \quad L_I = e_I + \frac{g_I}{r};$$

and from them we can reconstruct the physical fields. We are particularly interested in the metric. We need \hat{f} and $\hat{\omega}$

$$\hat{\omega} = \omega_5 (dr + \cos \theta d\varphi)$$

$$\omega_5 = M + 16\sqrt{2} C_{IJK} \Phi^I \Phi^J \Phi^K H^2 + 8\sqrt{2} L_I \Phi^I / H;$$

If we want a static solution we must set to zero M and some of the Φ 's and L 's so that $\omega_5 = 0$. In general we cannot eliminate the constant in the harmonic functions if we want the solution to be asymptotically flat. If we set all of them to zero we can always adjust M to get $\omega_5 = 0$ even if all the others are $\neq 0$. Setting the constants to zero is equivalent to take the $r \rightarrow 0$ limit and we will later see what happens in that case.

As for \hat{f} , we have $h_I / \hat{f} = L_I + 8 C_{IJK} \Phi^J \Phi^K / H$;

let us give an example of how to extract \hat{f} from these relations: if the RSG model has a scalar manifold that is a symmetric Riemannian space

$$C^{IJK} C_J (L_I C_{NP})_K = \frac{1}{27} \delta^I_{(L} C_{MNP)} \quad (C^{IJK} = C_{IJK})$$

$$\Rightarrow h^I = 27 C^{IJK} h_J h_K \Rightarrow 27 C^{IJK} h_I h_J h_K = 1; \quad 27 \underbrace{C^{IJK} h_I h_J h_K}_{\frac{1}{\hat{f}^3}} = \hat{f}^{-3}$$

$$\Rightarrow \hat{f}^{-1} = \left\{ C^{IJK} (L_I + 8 C_{I\Phi^2}/H) (L_J + 8 C_{J\Phi^2}/H) (L_K + 8 C_{K\Phi^2}/H) \right\}^{1/3}$$

For large z \hat{f}^{-1} - constant that can be normalised to 1 if it does not
vanish

For $z \rightarrow 0$ \hat{f}^{-1} - constant $\frac{1}{2}$

$$\Rightarrow ds^2 \sim \frac{z^2}{(\text{const})^3} dt^2 - \text{const} \frac{1}{z} \left[\frac{1}{z} dt^2 + 2(z^2 + \varphi)^2 + 2 d\Omega^2(z) \right]$$

$AdS_2 \times S^3$

The constant is related to the entropy $(\text{const})^{3/2}$ and is a function of the charges q_I and "dipole moments p^{\pm} ".

If ω_S does not vanish and, at $z \rightarrow \infty$ $\omega_S \sim \mathcal{F}/z$, then the solution has 2
angular momenta \mathcal{F} and the near-horizon limit includes $\left[dt + \frac{\mathcal{F}}{z} (dz + \cos \theta d\varphi) \right]$
 \Rightarrow 1-parameter family that interpolates between $AdS_2 \times S^3$ and $AdS_3 \times S^2$



Black rings

miércoles, 30 de noviembre de 2016 18:54

In $d=5$ BHs can have two independent angular momenta that interacted them. The supersymmetric, asymptotically flat ones only have 1. One can have 2, but then the horizon of the solution no longer has the topology of a sphere. It's a torus $S^1 \times S^2 \rightarrow$ "black ring".

These solutions cannot exist in $d=4$ (Hawking: the topology of an event horizon is always S^2 in $d=4$), which makes them interesting.

Constructing the simplest supersymmetric BR in five dimensions is really simple: choose the functions

$$H = \frac{1}{r} ; \quad L = 1 + \frac{q_0 - a^2}{4} N ; \quad K = -\frac{a}{2} N ; \quad M = \frac{3a}{4} \left(1 - \frac{R^2}{4} N \right) ;$$

$$\text{with } N = \frac{1}{|z - z_1|} ; \quad \vec{x}_1 = (0, 0, -R^2/4)$$

The values of the coefficients ensure asymptotic flatness and integrability of ω plus absence of CTCs, Chirons/Dicke strings etc.

$$\hat{f}^{-1} = 1 + q_0 N - a^2 N (1 - 2N) ;$$

$$\omega = (F - \cos \theta G) d\varphi + (F - G) d\psi ;$$

$$F = \frac{3a}{4} \left[1 - \left(2 + \frac{R^2}{4} \right) N \right]$$

$$G = \frac{a}{16} 2 N^2 \left[(3q_0 - a^2) + 2a^2 2N \right] ;$$

$$\text{Then } M = \sqrt{3} q_0 ; \quad J_1 = \frac{1}{2\sqrt{3}} a (3q_0 - a^2) ; \quad J_2 = \frac{1}{2\sqrt{3}} a (6R^2 + 3q_0 - a^2)$$

Checking the regularity etc. is complicated and we will not do it here.

Solutions with non-Abelian Yang-Mills fields

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The next step in the construction of asymptotically-flat supersymmetric BH solutions is the inclusion of non-Abelian Yang-Mills fields. Let's consider $N=1, d=5$ SYM theories with an $SU(2)$ gauging plus, possibly, some Abelian ungauged fields. It is important to remember that we do not want $SU(2)$ to gauge R -symmetry. Those terms would give rise to a non-vanishing scalar potential. SYM theories have $V=0$. For the sake of clarity, we are going to consider a particular model which we have already mentioned and which can be embedded in string theory $G_{0xy} = \frac{1}{8!} \eta_{xy}$; $\eta = \text{diag}(+ \dots -)$; $x, y = 1, \dots, 10, 5 > 3$ let's take just $10, 5 = 4$. The Abelian sector is $I=0, 1$ and the $SU(2)$ is $2+1 = 2, 3, 4$ ($\alpha=1, 2, 3$)

The equations that we need to solve are

$$d *_3 d M = 0; \quad d *_3 d H = 0; \quad d *_3 d \Phi^0 = 0; \quad d *_3 d \Phi^1 = 0;$$

$$d *_3 d L_0 = 0; \quad d *_3 d L_1 = 0;$$

non-Abelian sector

$$\left\{ \begin{aligned} *_3 \not\partial \Phi^{\alpha+1} &= \tilde{F}^{\alpha+1}; \\ \not\partial *_3 \not\partial L_{\alpha+1} &= g^2 \left[\Phi^{\alpha+1} \Phi^{\alpha+1} L_{\alpha+1} - \Phi^{\alpha+1} \Phi^{\alpha+1} L_{\alpha+1} \right]; \\ *_3 d \omega &= H d M - M d H + 3\sqrt{2} \left(\Phi^0 d L_0 + \Phi^1 d L_1 - L_0 d \Phi^0 - L_1 d \Phi^1 \right) \\ &\quad + 3\sqrt{2} \left(\Phi^{\alpha+1} \not\partial L_{\alpha+1} - L_{\alpha+1} \not\partial \Phi^{\alpha+1} \right); \end{aligned} \right.$$

Abelian sector

and we have to take into account that, for this model

$$\hat{f}^{-1} = H^{-1} \left\{ \frac{1}{4} (6H L_0 + 8\eta_{xy} \Phi^x \Phi^y) \left[9H^2 \eta^{xy} L_x L_y + 48H \Phi^0 L_x \Phi^x + 64(\Phi^0)^2 \eta^{xy} \Phi^x \Phi^y \right] \right\}^{1/3}$$

just $L_0, L_1 \neq 0$ give a regular BH $\hat{f}^{-1} = \left\{ \frac{2f}{2} L_0 (L_1)^2 \right\}^{1/3}$

Adding $\Phi^{\alpha+1} \neq 0$ $\hat{f}^{-1} = \left\{ \frac{2f}{2} \left(L_0 - \frac{4}{3} \frac{\Phi^{\alpha+1} \Phi^{\alpha+1}}{H} \right) (L_1)^2 \right\}^{1/3}$

Keeping $M=0 \Rightarrow \omega=0$ and we only need to choose the solution of the $SU(2)$ Bogomol'nyi equations.

If we are after spherically-symmetric solutions we can use the "hedgehog ansatz" (all the spherically-symmetric solutions fit in it)

$$\hat{A}^{2+1} = h(r) \varepsilon^{\alpha\beta} dx^\alpha dx^\beta; \quad \hat{\Phi}^{2+1} = f(r) X^2;$$

Plugging this ansatz into the Bogomol'nyi equations we arrive at a system of ODEs for f and h ($g=1$ for simplicity)

$$\begin{cases} r h' + 2h + f(h^2 r) = 0; \\ r(h-f) - r^2 h(h-f) = 0; \end{cases}$$

with 2 families of solutions

$$\textcircled{1} (\mu, s) \rightarrow \begin{cases} r f = -\frac{1}{2} [1 - \mu r \cosh(\mu r + s)]; \\ r h = \frac{1}{2} \left[\frac{\mu r}{\sinh(\mu r + s)} - 1 \right]; \end{cases} \quad \begin{array}{l} s=0 \rightarrow \text{BPS 't Hooft-} \\ \text{Polyakov} \\ \text{(the only regular)} \end{array}$$

$$\textcircled{2} \lambda \rightarrow \begin{cases} r f = -\frac{1}{2(1+\lambda^2 r^2)}; \\ r h = r f; \end{cases} \quad \begin{array}{l} \lambda=0 \rightarrow \text{de Yang } SO(2) \\ \text{monopole} \\ \lambda \neq 0 \rightarrow \text{"colored monopole"} \end{array}$$

The latter is related via duality to the BPST instanton with $H = \frac{1}{2}$;

$$\hat{A}^{2+1} = \frac{-1}{1 + \frac{\lambda^2 r^2}{4}} \varepsilon^{\alpha\beta} dx^\alpha dx^\beta; \quad \hat{F} = +\hat{F};$$

From the point of view of the metric, all we need are the "Higgs fields"

$$\hat{\Phi}^{2+1} = -\frac{1}{2(1+\lambda^2 r^2)} \frac{X^2}{2}; \quad \Rightarrow \quad \boxed{\frac{\hat{\Phi}^{2+1} \hat{\Phi}^{2+1}}{4} = \frac{1}{2^2(1+\lambda^2 r^2)^2}}$$

When $\lambda \rightarrow 0$ $\frac{\hat{\Phi}^{2+1} \hat{\Phi}^{2+1}}{4} \sim \frac{1}{2} \Rightarrow$ like an Abelian field, arbitrary to the entropy

When $\lambda \rightarrow \infty$ $\frac{\hat{\Phi}^{2+1} \hat{\Phi}^{2+1}}{4} \sim \frac{1}{2^3} \Rightarrow$ falls much faster and should not contribute to the mass \Rightarrow here!

Then, choosing $L_{0,1} = a_0 + 4 \frac{q_0}{2}$;

$$\hat{f}^{-1} = \left\{ \frac{2F}{2} \left[a_0 + 4 \frac{q_0}{2} - \frac{4}{3g^2} \frac{1}{2(1+\lambda^2 r^2)^2} \right] \left(a_1 + \frac{4q_1}{2} \right)^2 \right\}^{1/6}$$

$$[\vec{1}_r, \vec{1}_s] = -\varepsilon_{rs} \hat{T}_t; \quad \Rightarrow \quad F^2 = \lambda A^2 - \frac{1}{2} g \varepsilon^{\alpha\beta} A^S_{\alpha} A^t_{\beta}$$

$$\begin{aligned}
 \text{For } \lambda \rightarrow \infty \quad f^{-1} &= \left\{ \frac{27}{2} a_0 a_1^2 + 4(a_1^2 q_0 + 2a_0 a_1 q_1) \frac{1}{\lambda} + \mathcal{O}\left(\frac{1}{\lambda^2}\right) \right\}^{1/3} \\
 &= 3 \underbrace{\left(\frac{a_0 a_1^2}{2}\right)^{1/3}}_{\frac{1}{2}} \left\{ 1 + \underbrace{\frac{4}{3} \frac{(a_1^2 q_0 + 2a_0 a_1 q_1)}{27 a_0 a_1^2}}_{\equiv M} \frac{1}{\lambda} \right\} \\
 &\qquad\qquad\qquad \equiv M = \frac{8}{27} \left(\frac{q_0}{a_0} + 2 \frac{q_1}{a_1} \right) \leftarrow \text{central charge} \\
 &\qquad\qquad\qquad \text{Independent of } g!
 \end{aligned}$$

$$\text{For } \lambda \rightarrow 0 \quad f^{-1} \sim \left\{ \frac{27}{2} \underbrace{\left(4q_0 - \frac{4}{2g^2}\right)(4q_1)^2}_{R^2} \right\}^{1/3} \frac{1}{\lambda}$$

$$\Delta \sim R^3 \sim \left\{ \right\}^{1/2}$$

\downarrow
 Entropy of the BH depends on $\frac{1}{g}$! \leftarrow then the Abelian one.

Asymptotically-AdS5 solutions

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The construction of supersymmetric asymptotically-AdS5 is much complicated than the asymptotically-flat because now the Kähler base space is different for each different solution while in the asymptotically-flat case one could have many different solutions with the same hyperkähler base space. This is one of the reasons why one needs to know more about 4-dimensional Kähler manifolds.

To give some idea of the complexity of the problem, we are about by reviewing has the only maximally supersymmetric solution (AdS5) occurs in this setting.

Gutowski and Reall proved that AdS5 always appears with $\overline{\mathbb{CP}}^2$ (a.k.a. Bergman space, $SU(1,2)/U(2)$, universal hypermultiplet space) as base space.

Indeed, if we define AdS5 as the hyperboloid $z^0 \bar{z}^0 - z^i \bar{z}^i = 1$ in $\mathbb{C}^{1,2}$ with the canonical metric $ds^2 = dz^0 d\bar{z}^0 - dz^i d\bar{z}^i$, defining $z^0 = |z^0| e^{it}$, $z^i = z^0 \xi^i$, $\Rightarrow |z^0|^{-2} = 1 - \xi^i \bar{\xi}^i$

$$ds^2 = (dt + Q)^2 - g_{i\bar{j}} d\xi^i d\bar{\xi}^{\bar{j}}; \quad \leftarrow \text{AdS}_5$$

$$g_{i\bar{j}} = e^k [\delta_{i\bar{j}} + e^k \bar{\xi}^{\bar{i}} \xi^{\bar{j}}] \quad \leftarrow \overline{\mathbb{CP}}^2$$

$$e^{-k} = 1 - \xi^i \bar{\xi}^i \text{ is the Kähler potential.}$$

$$Q = \frac{i}{2} e^k (\bar{\xi}^{\bar{i}} d\xi^i - \text{c.c.}) \text{ is the Kähler 1-form}$$

$$F_{i\bar{j}} = -\frac{1}{2} (\partial_i Q_{\bar{j}} - \partial_{\bar{j}} Q_i) = \frac{i}{2} g_{i\bar{j}} \text{ is the Kähler 2-form}$$

In order to use our results we need to write the metric of $\overline{\mathbb{CP}}^2$ in the canonical form associated to one of its isometries. There are 3 simple possibilities.

$$\textcircled{k=1} \quad \xi^i = \text{th} \rho \cos \frac{\theta}{2} e^{-\frac{i}{2}(z+\varphi)}; \quad \xi^{\bar{i}} = \text{th} \rho \sin \frac{\theta}{2} e^{-\frac{i}{2}(z-\varphi)}$$

$$\rightarrow ds^2_{\overline{\mathbb{CP}}^2} = d\rho^2 + \frac{1}{4} \text{th}^2 \rho d\theta^2 + \frac{1}{4} \text{th}^2 \rho d\Omega^2_{(2,1)}$$

where $\lambda \Omega^2_{(2,1)} = \lambda \theta^2 + \cos^2 \theta \lambda \varphi^2$

These are, basically, the global coordinates of $HS_0: z = \psi + zt$

$$\lambda S^2_{MS_5} = du^2 g \lambda t^2 - \lambda g^2 - \lambda u^2 g \lambda \Omega^2_{(3,1)}$$

$$\lambda \Omega^2_{(3,1)} = \frac{1}{4} \left[(\lambda \psi + \cos \theta \lambda \varphi)^2 + \lambda \Omega^2_{(2,1)} \right]$$

$$(\lambda = \lambda u g \rightarrow \text{usual coordinates})$$

If, before this, we define

$$x^1 = \frac{1}{2} g \frac{\theta}{2} \cos \varphi; \quad \rho^1 = \frac{1}{4} \lambda u^2 g; \quad x^3 = \frac{1}{2} g \frac{\theta}{2} \sin \varphi$$

$$\rightarrow \lambda S^2_{\mathbb{CP}^2} = H^{-1} (\lambda z + \varphi)^2 + H \left\{ \lambda \rho^{1^2} + W^2 \left[(\lambda x^1)^2 + (\lambda x^3)^2 \right] \right\}$$

with $(\rho^1 \rightarrow \rho)$

$$H^{-1} = g (1 + 4g); \quad HW^2 = g \left\{ \frac{4}{1 + [(x^1)^2 + (x^3)^2]} \right\}^2$$

conformal factor of the sphere metric $\bar{\Phi}_{(1)}$

$$\varphi = \varphi_{(1)} = 2 \frac{x^1 \lambda x^3 - x^3 \lambda x^1}{1 + [(x^1)^2 + (x^3)^2]}$$

There are another 2 simple ways of writing \mathbb{CP}^2 in this canonical form labeled by $k=1, 0, -1$:

$$H^{-1} = g (k + 4g); \quad HW^2 = g \bar{\Phi}_{(k)}(x^1, x^3); \quad \varphi = \varphi_{(k)};$$

$$\bar{\Phi}_{(k)} = \frac{4}{\{1 + k[(x^1)^2 + (x^3)^2]\}^2}; \quad \varphi_{(k)} = 2 \frac{x^3 \lambda x^1 - x^1 \lambda x^3}{1 + k[(x^1)^2 + (x^3)^2]}$$

$$\Rightarrow Q = 2g (\lambda z + \varphi_{(k)});$$

Imposed by these metrics, we can consider Kähler metrics with

$$H = H(\rho); \quad W^2 = \psi(\rho) \bar{\Phi}(x^1, x^3) \quad (\text{factorial})$$

$$\Rightarrow \left(\partial_1^2 + \partial_3^2 \right) H + \partial_\rho^2 (HW^2) = 0 \quad \Rightarrow \partial_\rho^2 (H\psi) = 0$$

$$H = \frac{k\rho + \beta}{4}; \quad H = \rho^\varepsilon / \psi(\rho); \quad \varepsilon = 0, 1 \quad \text{up to diff of } \rho.$$

This defines a huge class of Kähler metrics.

We also assume now that $\hat{f} = \hat{f}(\rho)$ only

Then, we consider the next equation

$$\begin{aligned} \mathcal{J}^{-1} &= \frac{1}{8g^2} \bar{\nabla}^2 \log W^2 = \frac{1}{8g^2 H} \bar{\nabla}^2 (\log \psi + \log \bar{\Phi}) \\ &= \frac{1}{8g^2 H} \left[\frac{1}{W^2} (\partial_s (W^2 \partial_s) + \partial_1^2 + \partial_3^2) (\log \psi + \log \bar{\Phi}) \right] \\ &= \frac{1}{8g^2 H \psi} \left[\partial_s (\psi \partial_s \log \psi) + \underbrace{\frac{(\partial_1^2 + \partial_3^2) \log \bar{\Phi}}{\bar{\Phi}}}_{\text{constant!}} \right] \rightarrow \text{Liouville's equation.} \end{aligned}$$

$$\Rightarrow \boxed{\bar{\Phi} = \bar{\Phi}(k)}$$

The next equation is

$$gK = \partial_s \log W^2 = \partial_s \psi \Rightarrow \text{determines linkers of } \psi.$$

The next is

$$\bar{\nabla}^2 M = -\sqrt{3} g L (gK L + 2\partial_s L)$$

Integrating once

$$\rightarrow M' = \frac{\alpha}{\psi} - \sqrt{3} g L^2;$$

and using this result to eliminate M from the next equation

$$\bar{\nabla}^2 L = 4H \left(\frac{g}{\psi} L\right)^2 - \frac{2}{3} L (gK)^2 - \frac{4}{3} g L K' - \frac{1}{3} g K L' + \frac{4}{\sqrt{3}} g L M'$$

we get

$$L'' + \frac{4}{3} L' \frac{\psi'}{\psi} + \frac{4}{3} L \frac{\psi''}{\psi} - \frac{2}{3} L \left(\frac{\psi'}{\psi}\right)^2 - \frac{4}{\sqrt{3}} \frac{2g\psi^6}{\psi^2} = 0$$

which, together with the equation that defines L in terms of f and k, H

$$L = \frac{\psi}{8g^2 \psi^6} \left\{ -\frac{2k}{\psi} - \frac{2}{3} \left(\frac{\psi'}{\psi}\right)^2 + \frac{\psi''}{\psi} \right\}$$

gives the following 4th-order equations:

$$\varepsilon = 0 \rightarrow -32\sqrt{3} \frac{2g^3}{\psi^3} + 4k (\psi')^2 - 8k \psi \psi'' + 3\psi^2 \psi'''' = 0;$$

$$\begin{aligned} \varepsilon = 1 \rightarrow 96\sqrt{3} \frac{2g^3}{\psi^3} \psi^4 + 4g (\psi')^2 (-3k\psi + \psi') + 12\psi (2k\psi - \psi') (-\psi' + \psi \psi'') \\ + 9\psi^2 (4k - 2\psi'' + 2g\psi'''' - \psi^2 \psi''''') = 0 \end{aligned}$$

Simplest case: 4 polynomial eq

For simplicity, we will only review the $\epsilon = 1$ solutions

$$\psi = \frac{1}{a} \left[c g^3 + g^2 + b g + \frac{b^2}{3(1-ak)} \right]$$

$$c f \quad \alpha = \frac{1 + 3ak + 3bc \left(\frac{3bc}{1-ak} - 2(1-2ak) \right)}{24 \sqrt{3} a^3 g^3}$$

4 indep parameters
 a, b, c, k
 (one lost by rescaling)

$$\Rightarrow \hat{f} = \frac{4a \left(\frac{g}{\sqrt{3}} \right)^2 g}{c g + \frac{1-ak}{3}};$$

$$\boxed{\frac{4a}{c} \left(\frac{g}{\sqrt{3}} \right)^2 = 1 \rightarrow \text{normalization}}$$

$$H = \frac{a g}{c g^3 + g^2 + b g + \frac{b^2}{3(1-ak)}};$$

$$W^2 H = g \mathbb{F}(k);$$

$$\psi = \psi(k); \quad \rightarrow = 0 \text{ for asymptotically AdS}_5$$

$$\omega_2 = d + \frac{18c^2 g^3 + 18c(1-ak)g^2 + [9bc + 3(1-ak)^2]g + 2b(1-ak)}{16\sqrt{3}g^3 a^3 g^2}$$

AdS₅ + rotating BHs with 3 different near-horizon geometries.